NI-SCOPE Python API Documentation

Release 1.4.8

NI

DOCUMENTATION

1	About 1.1 Support Policy	1 1
2	Contributing	3
3	Support / Feedback	5
4	Bugs / Feature Requests 4.1 niscope module	7 7 8
5	License	151
6	Indices and tables	153
Ру	ython Module Index	155
In	ndex	157

CHAPTER

ONE

ABOUT

The **niscope** module provides a Python API for NI-SCOPE. The code is maintained in the Open Source repository for nimi-python.

1.1 Support Policy

niscope supports all the Operating Systems supported by NI-SCOPE.

It follows Python Software Foundation support policy for different versions of CPython.

2 Chapter 1. About

CHAPTER	
TWO	

CONTRIBUTING

We welcome contributions! You can clone the project repository, build it, and install it by following these instructions.

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THREE

SUPPORT / FEEDBACK

For support specific to the Python API, follow the processs in *Bugs / Feature Requests*. For support with hardware, the driver runtime or any other questions not specific to the Python API, please visit NI Community Forums.

CHAPTER

FOUR

BUGS / FEATURE REQUESTS

To report a bug or submit a feature request specific to Python API, please use the GitHub issues page.

Fill in the issue template as completely as possible and we will respond as soon as we can.

4.1 niscope module

4.1.1 Installation

As a prerequisite to using the **niscope** module, you must install the NI-SCOPE runtime on your system. Visit ni.com/downloads to download the driver runtime for your devices.

The nimi-python modules (i.e. for **NI-SCOPE**) can be installed with pip:

```
$ python -m pip install niscope~=1.4.8
```

4.1.2 Usage

The following is a basic example of using the **niscope** module to open a session to a High Speed Digitizer and capture a single record of 1000 points.

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```
# Find all record number 3
rec3 = [wfm for wfm in waveforms if wfm.record == 3]
```

If you need faster fetch performance, or to directly interface with SciPy, you can use the **fetch_into()** method instead of **fetch()**. See the fetch_into example.

Other usage examples can be found on GitHub.

4.1.3 API Reference

Session

Performs the following initialization actions:

- Creates a new IVI instrument driver and optionally sets the initial state of the following session properties: Range Check, Cache, Simulate, Record Value Coercions
- Opens a session to the specified device using the interface and address you specify for the resourceName
- Resets the digitizer to a known state if **resetDevice** is set to True
- Queries the instrument ID and verifies that it is valid for this instrument driver if the **IDQuery** is set to True
- Returns an instrument handle that you use to identify the instrument in all subsequent instrument driver method calls

Parameters

• resource_name (str) -

Caution: Traditional NI-DAQ and NI-DAQmx device names are not case-sensitive. However, all IVI names, such as logical names, are case-sensitive. If you use logical names, driver session names, or virtual names in your program, you must make sure that the name you use matches the name in the IVI Configuration Store file exactly, without any variations in the case of the characters.

Specifies the resource name of the device to initialize

For Traditional NI-DAQ devices, the syntax is DAQ::*n*, where *n* is the device number assigned by MAX, as shown in Example 1.

For NI-DAQmx devices, the syntax is just the device name specified in MAX, as shown in Example 2. Typical default names for NI-DAQmx devices in MAX are Dev1 or PXI1Slot1. You can rename an NI-DAQmx device by right-clicking on the name in MAX and entering a new name.

An alternate syntax for NI-DAQmx devices consists of DAQ::NI-DAQmx device name, as shown in Example 3. This naming convention allows for the use of an NI-DAQmx device in an application that was originally designed for a Traditional NI-DAQ device. For example,

if the application expects DAQ::1, you can rename the NI-DAQmx device to 1 in MAX and pass in DAQ::1 for the resource name, as shown in Example 4.

If you use the DAQ::*n* syntax and an NI-DAQmx device name already exists with that same name, the NI-DAQmx device is matched first.

You can also pass in the name of an IVI logical name or an IVI virtual name configured with the IVI Configuration utility, as shown in Example 5. A logical name identifies a particular virtual instrument. A virtual name identifies a specific device and specifies the initial settings for the session.

Exam- ple	Device Type	Syntax
1	Traditional NI-DAQ device	DAQ::1 (1 = device number)
2	NI-DAQmx device	myDAQmxDevice (myDAQmxDevice = device name)
3	NI-DAQmx device	DAQ::myDAQmxDevice (myDAQmxDevice = device name)
4	NI-DAQmx device	DAQ::2 (2 = device name)
5	IVI logical name or IVI virtual name	myLogicalName (myLogicalName = name)

• id_query (bool) – Specify whether to perform an ID query.

When you set this parameter to True, NI-SCOPE verifies that the device you initialize is a type that it supports.

When you set this parameter to False, the method initializes the device without performing an ID query.

Defined Values

True—Perform ID query False—Skip ID query

Default Value: True

reset_device (bool) – Specify whether to reset the device during the initialization process.

Default Value: True

Defined Values

True (1)—Reset device

False (0)—Do not reset device

Note: For the NI 5112, repeatedly resetting the device may cause excessive wear on the electromechanical relays. Refer to NI 5112 Electromechanical Relays for recommended programming practices.

• **options** (*dict*) – Specifies the initial value of certain properties for the session. The syntax for **options** is a dictionary of properties with an assigned value. For example:

```
{ 'simulate': False }
```

You do not have to specify a value for all the properties. If you do not specify a value for a property, the default value is used.

```
Advanced Example: { 'simulate': True, 'driver_setup': { 'Model': '<model number>', 'BoardType': '<type>' } }
```

Property	Default
range_check	True
query_instrument_status	False
cache	True
simulate	False
record_value_coersions	False
driver_setup	{}

• grpc_options (niscope.GrpcSessionOptions) - MeasurementLink gRPC session options

Methods

abort

```
niscope.Session.abort()
```

Aborts an acquisition and returns the digitizer to the Idle state. Call this method if the digitizer times out waiting for a trigger.

acquisition status

```
niscope.Session.acquisition_status()
```

Returns status information about the acquisition to the **status** output parameter.

Return type

```
niscope.AcquisitionStatus
```

Returns

Returns whether the acquisition is complete, in progress, or unknown.

Defined Values

COMPLETE

IN_PROGRESS

STATUS_UNKNOWN

add waveform processing

niscope.Session.add_waveform_processing(meas_function)

Adds one measurement to the list of processing steps that are completed before the measurement. The processing is added on a per channel basis, and the processing measurements are completed in the same order they are registered. All measurement library parameters—the properties starting with "meas_"—are cached at the time of registering the processing, and this set of parameters is used during the processing step. The processing measurements are streamed, so the result of the first processing step is used as the input for the next step. The processing is done before any other measurements.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].add_waveform_processing()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.add_waveform_processing()

Parameters

meas_function (*niscope.ArrayMeasurement*) – The array measurement to add.

auto_setup

niscope.Session.auto_setup()

Automatically configures the instrument. When you call this method, the digitizer senses the input signal and automatically configures many of the instrument settings. If a signal is detected on a channel, the driver chooses the smallest available vertical range that is larger than the signal range. For example, if the signal is a 1.2 $V_{pk\text{-}pk}$ sine wave, and the device supports 1 V and 2 V vertical ranges, the driver will choose the 2 V vertical range for that channel.

If no signal is found on any analog input channel, a warning is returned, and all channels are enabled. A channel is considered to have a signal present if the signal is at least 10% of the smallest vertical range available for that channel.

The following settings are changed:

General		
Acquisition mode	Normal	
Reference clock	Internal	
Vertical		
Vertical coupling	AC (DC for NI 5621)	
Vertical bandwidth	Full	
Vertical range	Changed by auto setup	
Vertical offset	0 V	
Probe attenuation	Unchanged by auto setup	
Input impedance	Unchanged by auto setup	
Horizontal		
Sample rate	Changed by auto setup	
Min record length	Changed by auto setup	
Enforce realtime	True	
Number of Records	Changed to 1	
Triggering		
Trigger type	Edge if signal present, otherwise immediate	
Trigger channel	Lowest numbered channel with a signal present	
Trigger slope	Positive	
Trigger coupling	DC	
Reference position	50%	
Trigger level	50% of signal on trigger channel	
Trigger delay	0	
Trigger holdoff	0	
Trigger output	None	

clear waveform measurement stats

 $\verb|niscope.Session.clear_waveform_measurement_stats| (clearable_measurement_function=niscope. ClearableMeasurement_stats)| (clearable_measurement_function=niscope. ClearableMeasurement_stats)| (clearable_measurement_function=niscope. ClearableMeasurement_stats)| (clearable_measurement_function=niscope. ClearableMeasurement_stats)| (clearable_measurement_stats)| (cleara$

Clears the waveform stats on the channel and measurement you specify. If you want to clear all of the measurements, use *ALL_MEASUREMENTS* in the **clearableMeasurementFunction** parameter.

Every time a measurement is called, the statistics information is updated, including the min, max, mean, standard deviation, and number of updates. This information is fetched with niscope. Session._fetch_measurement_stats(). The multi-acquisition array measurements are also cleared with this method.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].clear_waveform_measurement_stats()

To call the method on all channels, you can call it directly on the *niscope*. Session.

Example: my_session.clear_waveform_measurement_stats()

Parameters

clearable_measurement_function (niscope.ClearableMeasurement) — The scalar measurement or array measurement to clear the stats for.

clear waveform processing

niscope.Session.clear_waveform_processing()

Clears the list of processing steps assigned to the given channel. The processing is added using the <code>niscope.Session.add_waveform_processing()</code> method, where the processing steps are completed in the same order in which they are registered. The processing measurements are streamed, so the result of the first processing step is used as the input for the next step. The processing is also done before any other measurements.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].clear_waveform_processing()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.clear_waveform_processing()

close

niscope.Session.close()

When you are finished using an instrument driver session, you must call this method to perform the following actions:

- Closes the instrument I/O session.
- Destroys the IVI session and all of its properties.
- Deallocates any memory resources used by the IVI session.

Note: This method is not needed when using the session context manager

commit

niscope.Session.commit()

Commits to hardware all the parameter settings associated with the task. Use this method if you want a parameter change to be immediately reflected in the hardware. This method is not supported for Traditional NI-DAQ (Legacy) devices.

configure chan characteristics

niscope.Session.configure_chan_characteristics(input_impedance, max_input_frequency)

Configures the properties that control the electrical characteristics of the channel—the input impedance and the bandwidth.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].configure_chan_characteristics()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.configure_chan_characteristics()

Parameters

- **input_impedance** (*float*) The input impedance for the channel; NI-SCOPE sets *niscope*. *Session*. *input_impedance* to this value.
- max_input_frequency (float) The bandwidth for the channel; NI-SCOPE sets niscope. Session.max_input_frequency to this value. Pass 0 for this value to use the hardware default bandwidth. Pass -1 for this value to achieve full bandwidth.

configure equalization filter coefficients

niscope.Session.configure_equalization_filter_coefficients(coefficients)

Configures the custom coefficients for the equalization FIR filter on the device. This filter is designed to compensate the input signal for artifacts introduced to the signal outside of the digitizer. Because this filter is a generic FIR filter, any coefficients are valid. Coefficient values should be between +1 and -1.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].configure_equalization_filter_coefficients()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.configure_equalization_filter_coefficients()

Parameters

coefficients (list of float) -The custom coefficients for These coefficients should equalization FIR filter on the device. be between +1 and -1. You can obtain the number of coefficients from the :py:attr: `niscope.Session.equalization num coefficients <cvi:py:attr:niscope.Session.equalization num coefficients.html>` property. The :py:attr: `niscope.Session.equalization_filter_enabled <cvi:py:attr:niscope.Session.equalization_filter_enabled.html>`___ property must be set to TRUE to enable the filter.

configure horizontal timing

niscope.Session.configure_horizontal_timing(min_sample_rate, min_num_pts, ref_position, num_records, enforce_realtime)

Configures the common properties of the horizontal subsystem for a multirecord acquisition in terms of minimum sample rate.

- min_sample_rate (float) The sampling rate for the acquisition. Refer to niscope.Session.min_sample_rate for more information.
- min_num_pts (int) The minimum number of points you need in the record for each channel; call niscope.Session.ActualRecordLength() to obtain the actual record length used.

Valid Values: Greater than 1; limited by available memory

Note: One or more of the referenced methods are not in the Python API for this driver.

- **ref_position** (*float*) The position of the Reference Event in the waveform record specified as a percentage.
- num_records (int) The number of records to acquire
- **enforce_realtime** (*bool*) Indicates whether the digitizer enforces real-time measurements or allows equivalent-time (RIS) measurements; not all digitizers support RIS—refer to Features Supported by Device for more information.

Default value: True

Defined Values

True—Allow real-time acquisitions only

False—Allow real-time and equivalent-time acquisitions

configure_trigger_digital

niscope.Session.configure_trigger_digital(trigger_source,

slope=niscope.TriggerSlope.POSITIVE, holdoff=hightime.timedelta(seconds=0.0), delay=hightime.timedelta(seconds=0.0))

Configures the common properties of a digital trigger.

When you initiate an acquisition, the digitizer waits for the start trigger, which is configured through the <code>niscope.Session.acq_arm_source</code> (Start Trigger Source) property. The default is immediate. Upon receiving the start trigger the digitizer begins sampling pretrigger points. After the digitizer finishes sampling pretrigger points, the digitizer waits for a reference (stop) trigger that you specify with a method such as this one. Upon receiving the reference trigger the digitizer finishes the acquisition after completing posttrigger sampling. With each Configure Trigger method, you specify configuration parameters such as the trigger source and the amount of trigger delay.

Note: For multirecord acquisitions, all records after the first record are started by using the Advance Trigger Source. The default is immediate.

You can adjust the amount of pre-trigger and post-trigger samples using the reference position parameter on the <code>niscope.Session.configure_horizontal_timing()</code> method. The default is half of the record length.

Some features are not supported by all digitizers. Refer to Features Supported by Device for more information.

Digital triggering is not supported in RIS mode.

Parameters

- **trigger_source** (*str*) Specifies the trigger source. Refer to *niscope*. *Session.trigger_source* for defined values.
- **slope** (*niscope*. *TriggerSlope*) Specifies whether you want a rising edge or a falling edge to trigger the digitizer. Refer to *niscope*. *Session*. *trigger_slope* for more information.
- holdoff (hightime.timedelta, datetime.timedelta, or float in seconds) The length of time the digitizer waits after detecting a trigger before enabling NI-SCOPE to detect another trigger. Refer to niscope.Session. trigger_holdoff for more information.
- delay (hightime.timedelta, datetime.timedelta, or float in seconds) How long the digitizer waits after receiving the trigger to start acquiring data. Refer to niscope.Session.trigger_delay_time for more information.

configure trigger edge

```
niscope.Session.configure_trigger_edge(trigger_source, level, trigger_coupling, slope=niscope.TriggerSlope.POSITIVE, holdoff=hightime.timedelta(seconds=0.0), delay=hightime.timedelta(seconds=0.0))
```

Configures common properties for analog edge triggering.

When you initiate an acquisition, the digitizer waits for the start trigger, which is configured through the <code>niscope.Session.acq_arm_source</code> (Start Trigger Source) property. The default is immediate. Upon receiving the start trigger the digitizer begins sampling pretrigger points. After the digitizer finishes sampling pretrigger points, the digitizer waits for a reference (stop) trigger that you specify with a method such as this one. Upon receiving the reference trigger the digitizer finishes the acquisition after completing posttrigger sampling. With each Configure Trigger method, you specify configuration parameters such as the trigger source and the amount of trigger delay.

Note: Some features are not supported by all digitizers. Refer to Features Supported by Device for more information.

- **trigger_source** (*str*) Specifies the trigger source. Refer to *niscope*. *Session.trigger_source* for defined values.
- **level** (*float*) The voltage threshold for the trigger. Refer to *niscope*. *Session*. *trigger_level* for more information.
- **trigger_coupling** (niscope.TriggerCoupling) Applies coupling and filtering options to the trigger signal. Refer to niscope.Session.trigger_coupling for more information.
- **slope** (*niscope.TriggerSlope*) Specifies whether you want a rising edge or a falling edge to trigger the digitizer. Refer to *niscope.Session.trigger_slope* for more information.
- holdoff (hightime.timedelta, datetime.timedelta, or float in seconds) The length of time the digitizer waits after detecting a trigger before

enabling NI-SCOPE to detect another trigger. Refer to niscope. Session. trigger_holdoff for more information.

delay (hightime.timedelta, datetime.timedelta, or float in seconds) – How long the digitizer waits after receiving the trigger to start acquiring data. Refer to niscope.Session.trigger_delay_time for more information.

configure_trigger_hysteresis

```
niscope.Session.configure_trigger_hysteresis(trigger_source, level, hysteresis, trigger_coupling, slope=niscope.TriggerSlope.POSITIVE, holdoff=hightime.timedelta(seconds=0.0), delay=hightime.timedelta(seconds=0.0))
```

Configures common properties for analog hysteresis triggering. This kind of trigger specifies an additional value, specified in the **hysteresis** parameter, that a signal must pass through before a trigger can occur. This additional value acts as a kind of buffer zone that keeps noise from triggering an acquisition.

When you initiate an acquisition, the digitizer waits for the start trigger, which is configured through the <code>niscope.Session.acq_arm_source</code>. The default is immediate. Upon receiving the start trigger the digitizer begins sampling pretrigger points. After the digitizer finishes sampling pretrigger points, the digitizer waits for a reference (stop) trigger that you specify with a method such as this one. Upon receiving the reference trigger the digitizer finishes the acquisition after completing post-trigger sampling. With each Configure Trigger method, you specify configuration parameters such as the trigger source and the amount of trigger delay.

Note: Some features are not supported by all digitizers. Refer to Features Supported by Device for more information.

- **trigger_source** (*str*) Specifies the trigger source. Refer to *niscope*. *Session.trigger_source* for defined values.
- **level** (*float*) The voltage threshold for the trigger. Refer to *niscope*. *Session*. *trigger_level* for more information.
- **hysteresis** (*float*) The size of the hysteresis window on either side of the **level** in volts; the digitizer triggers when the trigger signal passes through the hysteresis value you specify with this parameter, has the slope you specify with **slope**, and passes through the **level**. Refer to *niscope*. *Session*. *trigger_hysteresis* for defined values.
- **trigger_coupling** (niscope.TriggerCoupling) Applies coupling and filtering options to the trigger signal. Refer to niscope.Session.trigger_coupling for more information.
- **slope** (*niscope.TriggerSlope*) Specifies whether you want a rising edge or a falling edge to trigger the digitizer. Refer to *niscope.Session.trigger_slope* for more information.
- holdoff (hightime.timedelta, datetime.timedelta, or float in seconds) The length of time the digitizer waits after detecting a trigger before

enabling NI-SCOPE to detect another trigger. Refer to niscope. Session. trigger_holdoff for more information.

• **delay** (hightime.timedelta, datetime.timedelta, or float in seconds) — How long the digitizer waits after receiving the trigger to start acquiring data. Refer to niscope.Session.trigger_delay_time for more information.

configure_trigger_immediate

niscope.Session.configure_trigger_immediate()

Configures common properties for immediate triggering. Immediate triggering means the digitizer triggers itself.

When you initiate an acquisition, the digitizer waits for a trigger. You specify the type of trigger that the digitizer waits for with a Configure Trigger method, such as niscope. Session. configure_trigger_immediate().

configure trigger software

niscope.Session.configure_trigger_software(holdoff=hightime.timedelta(seconds=0.0), delay=hightime.timedelta(seconds=0.0))

Configures common properties for software triggering.

When you initiate an acquisition, the digitizer waits for the start trigger, which is configured through the <code>niscope.Session.acq_arm_source</code> (Start Trigger Source) property. The default is immediate. Upon receiving the start trigger the digitizer begins sampling pretrigger points. After the digitizer finishes sampling pretrigger points, the digitizer waits for a reference (stop) trigger that you specify with a method such as this one. Upon receiving the reference trigger the digitizer finishes the acquisition after completing posttrigger sampling. With each Configure Trigger method, you specify configuration parameters such as the trigger source and the amount of trigger delay.

To trigger the acquisition, use niscope. Session.send_software_trigger_edge().

Note: Some features are not supported by all digitizers. Refer to Features Supported by Device for more information.

- holdoff (hightime.timedelta, datetime.timedelta, or float in seconds) The length of time the digitizer waits after detecting a trigger before enabling NI-SCOPE to detect another trigger. Refer to niscope.Session. trigger_holdoff for more information.
- delay (hightime.timedelta, datetime.timedelta, or float in seconds) How long the digitizer waits after receiving the trigger to start acquiring data. Refer to niscope.Session.trigger_delay_time for more information.

configure_trigger_video

```
niscope.Session.configure_trigger_video(trigger_source, signal_format, event, polarity, trigger_coupling, enable_dc_restore=False, line_number=1, holdoff=hightime.timedelta(seconds=0.0), delay=hightime.timedelta(seconds=0.0))
```

Configures the common properties for video triggering, including the signal format, TV event, line number, polarity, and enable DC restore. A video trigger occurs when the digitizer finds a valid video signal sync.

When you initiate an acquisition, the digitizer waits for the start trigger, which is configured through the <code>niscope.Session.acq_arm_source</code> (Start Trigger Source) property. The default is immediate. Upon receiving the start trigger the digitizer begins sampling pretrigger points. After the digitizer finishes sampling pretrigger points, the digitizer waits for a reference (stop) trigger that you specify with a method such as this one. Upon receiving the reference trigger the digitizer finishes the acquisition after completing posttrigger sampling. With each Configure Trigger method, you specify configuration parameters such as the trigger source and the amount of trigger delay.

Note: Some features are not supported by all digitizers. Refer to Features Supported by Device for more information.

Parameters

- **trigger_source** (*str*) Specifies the trigger source. Refer to *niscope*. *Session.trigger_source* for defined values.
- **signal_format** (*niscope.VideoSignalFormat*) Specifies the type of video signal sync the digitizer should look for. Refer to *niscope.Session.* tv_trigger_signal_format for more information.
- **event** (*niscope*. *VideoTriggerEvent*) Specifies the TV event you want to trigger on. You can trigger on a specific or on the next coming line or field of the signal.
- **polarity** (*niscope*. *VideoPolarity*) Specifies the polarity of the video signal sync.
- **trigger_coupling** (niscope.TriggerCoupling) Applies coupling and filtering options to the trigger signal. Refer to niscope.Session.trigger_coupling for more information.
- enable_dc_restore (bool) Offsets each video line so the clamping level (the portion of the video line between the end of the color burst and the beginning of the active image) is moved to zero volt. Refer to niscope.Session. enable_dc_restore for defined values.
- **line_number** (*int*) Selects the line number to trigger on. The line number range covers an entire frame and is referenced as shown on Vertical Blanking and Synchronization Signal. Refer to *niscope.Session.tv_trigger_line_number* for more information.

Default value: 1

• holdoff (hightime.timedelta, datetime.timedelta, or float in seconds) — The length of time the digitizer waits after detecting a trigger before enabling NI-SCOPE to detect another trigger. Refer to niscope.Session. trigger_holdoff for more information.

• delay (hightime.timedelta, datetime.timedelta, or float in seconds) — How long the digitizer waits after receiving the trigger to start acquiring data. Refer to niscope.Session.trigger_delay_time for more information.

configure_trigger_window

```
niscope.Session.configure_trigger_window(trigger_source, low_level, high_level, window_mode, trigger_coupling, holdoff=hightime.timedelta(seconds=0.0), delay=hightime.timedelta(seconds=0.0))
```

Configures common properties for analog window triggering. A window trigger occurs when a signal enters or leaves a window you specify with the **high level** or **low level** parameters.

When you initiate an acquisition, the digitizer waits for the start trigger, which is configured through the *niscope.Session.acq_arm_source* (Start Trigger Source) property. The default is immediate. Upon receiving the start trigger the digitizer begins sampling pretrigger points. After the digitizer finishes sampling pretrigger points, the digitizer waits for a reference (stop) trigger that you specify with a method such as this one. Upon receiving the reference trigger the digitizer finishes the acquisition after completing posttrigger sampling. With each Configure Trigger method, you specify configuration parameters such as the trigger source and the amount of trigger delay.

To trigger the acquisition, use <code>niscope.Session.send_software_trigger_edge()</code>.

Note: Some features are not supported by all digitizers.

- **trigger_source** (*str*) Specifies the trigger source. Refer to *niscope*. *Session.trigger_source* for defined values.
- **low_level** (*float*) Passes the voltage threshold you want the digitizer to use for low triggering.
- **high_level** (*float*) Passes the voltage threshold you want the digitizer to use for high triggering.
- window_mode (niscope.TriggerWindowMode) Specifies whether you want the trigger to occur when the signal enters or leaves a window.
- **trigger_coupling** (niscope.TriggerCoupling) Applies coupling and filtering options to the trigger signal. Refer to niscope.Session.trigger_coupling for more information.
- holdoff (hightime.timedelta, datetime.timedelta, or float in seconds) The length of time the digitizer waits after detecting a trigger before enabling NI-SCOPE to detect another trigger. Refer to niscope.Session. trigger_holdoff for more information.
- delay (hightime.timedelta, datetime.timedelta, or float in seconds) How long the digitizer waits after receiving the trigger to start acquiring data. Refer to niscope.Session.trigger_delay_time for more information.

configure_vertical

niscope.Session.configure_vertical(range, coupling, offset=0.0, probe_attenuation=1.0, enabled=True)

Configures the most commonly configured properties of the digitizer vertical subsystem, such as the range, offset, coupling, probe attenuation, and the channel.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].configure_vertical()

To call the method on all channels, you can call it directly on the *niscope*. Session.

Example: my_session.configure_vertical()

Parameters

- range (float) Specifies the vertical range Refer to niscope. Session. vertical_range for more information.
- **coupling** (*niscope*. *VerticalCoupling*) Specifies how to couple the input signal. Refer to *niscope*. *Session*. *vertical_coupling* for more information.
- **offset** (*float*) Specifies the vertical offset. Refer to *niscope*. Session. *vertical_offset* for more information.
- **probe_attenuation** (*float*) Specifies the probe attenuation. Refer to *niscope.Session.probe_attenuation* for valid values.
- **enabled** (*bool*) Specifies whether the channel is enabled for acquisition. Refer to *niscope*. *Session*. *channel_enabled* for more information.

disable

niscope.Session.disable()

Aborts any current operation, opens data channel relays, and releases RTSI and PFI lines.

export attribute configuration buffer

niscope.Session.export_attribute_configuration_buffer()

Exports the property configuration of the session to a configuration buffer.

You can export and import session property configurations only between devices with identical model numbers, channel counts, and onboard memory sizes.

This method verifies that the properties you have configured for the session are valid. If the configuration is invalid, NI-SCOPE returns an error.

Related Topics:

Properties and Property Methods

Setting Properties Before Reading Properties

Return type

bytes

Returns

Specifies the byte array buffer to be populated with the exported property configuration.

export_attribute_configuration_file

niscope.Session.export_attribute_configuration_file(file_path)

Exports the property configuration of the session to the specified file.

You can export and import session property configurations only between devices with identical model numbers, channel counts, and onboard memory sizes.

This method verifies that the properties you have configured for the session are valid. If the configuration is invalid, NI-SCOPE returns an error.

Related Topics:

Properties and Property Methods

Setting Properties Before Reading Properties

Parameters

file_path (*str*) – Specifies the absolute path to the file to contain the exported property configuration. If you specify an empty or relative path, this method returns an error. **Default file extension:** .niscopeconfig

fetch

niscope.Session.**fetch**(num_samples=None, relative_to=niscope.FetchRelativeTo.PRETRIGGER, offset=0, record_number=0, num_records=None, timeout=hightime.timedelta(seconds=5.0))

Returns the waveform from a previously initiated acquisition that the digitizer acquires for the specified channel. This method returns scaled voltage waveforms.

This method may return multiple waveforms depending on the number of channels, the acquisition type, and the number of records you specify.

Note: Some functionality, such as time stamping, is not supported in all digitizers.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].fetch()

To call the method on all channels, you can call it directly on the *niscope*. Session.

Example: my_session.fetch()

- num_samples (int) The maximum number of samples to fetch for each waveform. If the acquisition finishes with fewer points than requested, some devices return partial data if the acquisition finished, was aborted, or a timeout of 0 was used. If it fails to complete within the timeout period, the method raises.
- relative_to (niscope.FetchRelativeTo) Position to start fetching within one record.
- **offset** (*int*) Offset in samples to start fetching data within each record. The offset can be positive or negative.
- **record_number** (*int*) Zero-based index of the first record to fetch.
- num_records (int) Number of records to fetch. Use -1 to fetch all configured records.
- timeout (hightime.timedelta, datetime.timedelta, or float in seconds) The time to wait for data to be acquired; using 0 for this parameter tells NI-SCOPE to fetch whatever is currently available. Using -1 seconds for this parameter implies infinite timeout.

Return type

list of WaveformInfo

Returns

Returns a list of class instances with the following timing and scaling information about each waveform:

- relative_initial_x (float) the time (in seconds) from the trigger to the first sample in the fetched waveform
- absolute_initial_x (float) timestamp (in seconds) of the first fetched sample. This timestamp is comparable between records and acquisitions; devices that do not support this parameter use 0 for this output.
- x_increment (float) the time between points in the acquired waveform in seconds
- channel (str) channel name this waveform was acquired from
- record (int) record number of this waveform
- gain (float) the gain factor of the given channel; useful for scaling binary data with the following formula:

```
voltage = binarydata * gainfactor + offset
```

• **offset** (float) the offset factor of the given channel; useful for scaling binary data with the following formula:

```
voltage = binarydata * gainfactor + offset
```

 samples (array of float) floating point array of samples. Length will be of the actual samples acquired

fetch array measurement

niscope.Session.fetch_array_measurement(array_meas_function, meas_wfm_size=None, relative_to=niscope.FetchRelativeTo.PRETRIGGER, offset=0, record_number=0, num_records=None, meas_num_samples=None, timeout=hightime.timedelta(seconds=5.0))

Obtains a waveform from the digitizer and returns the specified measurement array. This method may return multiple waveforms depending on the number of channels, the acquisition type, and the number of records you specify.

Note: Some functionality, such as time stamping, is not supported in all digitizers.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].fetch_array_measurement()

To call the method on all channels, you can call it directly on the *niscope*. Session.

Example: my_session.fetch_array_measurement()

Parameters

- array_meas_function (niscope.ArrayMeasurement) The array measurement to perform.
- **meas_wfm_size** (*int*) The maximum number of samples returned in the measurement waveform array for each waveform measurement. Default Value: None (returns all available samples).
- **relative_to** (*niscope.FetchRelativeTo*) Position to start fetching within one record.
- **offset** (*int*) Offset in samples to start fetching data within each record. The offset can be positive or negative.
- **record_number** (*int*) Zero-based index of the first record to fetch.
- num_records (int) Number of records to fetch. Use None to fetch all configured records.
- **meas_num_samples** (*int*) Number of samples to fetch when performing a measurement. Use *None* to fetch the actual record length.
- timeout (hightime.timedelta, datetime.timedelta, or float in seconds) The time to wait in seconds for data to be acquired; using 0 for this parameter tells NI-SCOPE to fetch whatever is currently available. Using -1 for this parameter implies infinite timeout.

Return type

list of WaveformInfo

Returns

Returns a list of class instances with the following timing and scaling information about each waveform:

- relativeInitialX—the time (in seconds) from the trigger to the first sample in the fetched waveform
- **absoluteInitialX**—timestamp (in seconds) of the first fetched sample. This timestamp is comparable between records and acquisitions; devices that do not support this parameter use 0 for this output.
- xIncrement—the time between points in the acquired waveform in seconds
- channel-channel name this waveform was acquired from
- record-record number of this waveform
- gain—the gain factor of the given channel; useful for scaling binary data with the following formula:

voltage = binary data × gain factor + offset

 offset—the offset factor of the given channel; useful for scaling binary data with the following formula:

voltage = binary data × gain factor + offset

• samples-floating point array of samples. Length will be of actual samples acquired.

fetch into

niscope.Session.fetch_into(waveform, relative_to=niscope.FetchRelativeTo.PRETRIGGER, offset=0, record_number=0, num_records=None, timeout=hightime.timedelta(seconds=5.0))

Returns the waveform from a previously initiated acquisition that the digitizer acquires for the specified channel. This method returns scaled voltage waveforms.

This method may return multiple waveforms depending on the number of channels, the acquisition type, and the number of records you specify.

Note: Some functionality, such as time stamping, is not supported in all digitizers.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].fetch()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.fetch()

Parameters

• waveform (array.array("d")) – numpy array of the appropriate type and size that should be acquired as a 1D array. Size should be num_samples times number of waveforms. Call niscope.Session._actual_num_wfms() to determine the number of waveforms.

Types supported are

- numpy.float64
- numpy.int8
- numpy.in16
- numpy.int32

Example:

- relative_to (niscope.FetchRelativeTo) Position to start fetching within one record.
- **offset** (*int*) Offset in samples to start fetching data within each record. The offset can be positive or negative.
- **record_number** (*int*) Zero-based index of the first record to fetch.
- num_records (int) Number of records to fetch. Use -1 to fetch all configured records.
- timeout (hightime.timedelta, datetime.timedelta, or float in seconds) The time to wait in seconds for data to be acquired; using 0 for this parameter tells NI-SCOPE to fetch whatever is currently available. Using -1 for this parameter implies infinite timeout.

Return type

list of WaveformInfo

Returns

Returns a list of class instances with the following timing and scaling information about each waveform:

- relative_initial_x (float) the time (in seconds) from the trigger to the first sample in the fetched waveform
- absolute_initial_x (float) timestamp (in seconds) of the first fetched sample. This timestamp is comparable between records and acquisitions; devices that do not support this parameter use 0 for this output.
- x increment (float) the time between points in the acquired waveform in seconds
- channel (str) channel name this waveform was acquired from
- record (int) record number of this waveform
- gain (float) the gain factor of the given channel; useful for scaling binary data with the following formula:

```
voltage = binarydata * gainfactor + offset
```

• offset (float) the offset factor of the given channel; useful for scaling binary data with the following formula:

```
voltage = binarydata * gainfactor + offset
```

 samples (array of float) floating point array of samples. Length will be of the actual samples acquired

fetch_measurement_stats

```
niscope.Session.fetch_measurement_stats(scalar_meas_function, relative_to=niscope.FetchRelativeTo.PRETRIGGER, offset=0, record_number=0, num_records=None, timeout=hightime.timedelta(seconds=5.0))
```

Obtains a waveform measurement and returns the measurement value. This method may return multiple statistical results depending on the number of channels, the acquisition type, and the number of records you specify.

You specify a particular measurement type, such as rise time, frequency, or voltage peak-to-peak. The waveform on which the digitizer calculates the waveform measurement is from an acquisition that you previously initiated. The statistics for the specified measurement method are returned, where the statistics are updated once every acquisition when the specified measurement is fetched by any of the Fetch Measurement methods. If a Fetch Measurement method has not been called, this method fetches the data on which to perform the measurement. The statistics are cleared by calling <code>niscope.Session.clear_waveform_measurement_stats()</code>.

Many of the measurements use the low, mid, and high reference levels. You configure the low, mid, and high references with <code>niscope.Session.meas_chan_low_ref_level</code>, <code>niscope.Session.meas_chan_mid_ref_level</code>, and <code>niscope.Session.meas_chan_high_ref_level</code> to set each channel differently.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

```
Example: my_session.channels[ ... ].fetch_measurement_stats()
```

To call the method on all channels, you can call it directly on the *niscope*. Session.

Example: my_session.fetch_measurement_stats()

- **scalar_meas_function** (*niscope.ScalarMeasurement*) The scalar measurement to be performed on each fetched waveform.
- relative_to (niscope.FetchRelativeTo) Position to start fetching within one record.
- **offset** (*int*) Offset in samples to start fetching data within each record. The offset can be positive or negative.
- **record_number** (*int*) Zero-based index of the first record to fetch.
- num_records (int) Number of records to fetch. Use None to fetch all configured records.

• timeout (hightime.timedelta, datetime.timedelta, or float in seconds) — The time to wait in seconds for data to be acquired; using 0 for this parameter tells NI-SCOPE to fetch whatever is currently available. Using -1 for this parameter implies infinite timeout.

Return type

list of MeasurementStats

Returns

Returns a list of class instances with the following measurement statistics about the specified measurement:

- result (float): the resulting measurement
- mean (float): the mean scalar value, which is obtained by

averaging each fetch_measurement_stats call - **stdev** (float): the standard deviations of the most recent **numInStats** measurements - **min_val** (float): the smallest scalar value acquired (the minimum of the **numInStats** measurements) - **max_val** (float): the largest scalar value acquired (the maximum of the **numInStats** measurements) - **num_in_stats** (int): the number of times fetch_measurement_stats has been called - **channel** (str): channel name this result was acquired from - **record** (int): record number of this result

get_channel_names

niscope.Session.get_channel_names(indices)

Returns a list of channel names for given channel indices.

Parameters

indices (*basic sequence types*, *str*, *or int*) – Index list for the channels in the session. Valid values are from zero to the total number of channels in the session minus one. The index string can be one of the following formats:

- A comma-separated list—for example, "0,2,3,1"
- A range using a hyphen—for example, "0-3"
- A range using a colon—for example, "0:3"

You can combine comma-separated lists and ranges that use a hyphen or colon. Both out-of-order and repeated indices are supported ("2,3,0", "1,2,2,3"). White space characters, including spaces, tabs, feeds, and carriage returns, are allowed between characters. Ranges can be incrementing or decrementing.

Return type

list of str

Returns

The channel name(s) at the specified indices.

get_equalization_filter_coefficients

niscope.Session.get_equalization_filter_coefficients()

Retrieves the custom coefficients for the equalization FIR filter on the device. This filter is designed to compensate the input signal for artifacts introduced to the signal outside of the digitizer. Because this filter is a generic FIR filter, any coefficients are valid. Coefficient values should be between +1 and -1.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].get_equalization_filter_coefficients()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.get_equalization_filter_coefficients()

get_ext_cal_last_date_and_time

```
niscope.Session.get_ext_cal_last_date_and_time()
```

Returns the date and time of the last external calibration performed.

Return type

hightime.timedelta, datetime.timedelta, or float in seconds

Returns

Indicates the **date** of the last calibration. A hightime datetime object is returned, but only contains resolution to the day.

get ext cal last temp

```
niscope.Session.get_ext_cal_last_temp()
```

Returns the onboard temperature, in degrees Celsius, of an oscilloscope at the time of the last successful external calibration. The temperature returned by this node is an onboard temperature read from a sensor on the surface of the oscilloscope. This temperature should not be confused with the environmental temperature of the oscilloscope surroundings. During operation, the onboard temperature is normally higher than the environmental temperature. Temperature-sensitive parameters are calibrated during self-calibration. Therefore, the self-calibration temperature is usually more important to read than the external calibration temperature.

Return type

float

Returns

Returns the **temperature** in degrees Celsius during the last calibration.

get_self_cal_last_date_and_time

niscope.Session.get_self_cal_last_date_and_time()

Returns the date and time of the last self calibration performed.

Return type

hightime.timedelta, datetime.timedelta, or float in seconds

Returns

Indicates the **date** of the last calibration. A hightime datetime object is returned, but only contains resolution to the day.

get_self_cal_last_temp

niscope.Session.get_self_cal_last_temp()

Returns the onboard temperature, in degrees Celsius, of an oscilloscope at the time of the last successful self calibration. The temperature returned by this node is an onboard temperature read from a sensor on the surface of the oscilloscope. This temperature should not be confused with the environmental temperature of the oscilloscope surroundings. During operation, the onboard temperature is normally higher than the environmental temperature. Temperature-sensitive parameters are calibrated during self-calibration. Therefore, the self-calibration temperature is usually more important to read than the external calibration temperature.

Return type

float

Returns

Returns the **temperature** in degrees Celsius during the last calibration.

import attribute configuration buffer

niscope.Session.import_attribute_configuration_buffer(configuration)

Imports a property configuration to the session from the specified configuration buffer.

You can export and import session property configurations only between devices with identical model numbers, channel counts, and onboard memory sizes.

Related Topics:

Properties and Property Methods

Setting Properties Before Reading Properties

Note: You cannot call this method while the session is in a running state, such as while acquiring a signal.

Parameters

configuration (*bytes*) – Specifies the byte array buffer that contains the property configuration to import.

import_attribute_configuration_file

niscope.Session.import_attribute_configuration_file(file_path)

Imports a property configuration to the session from the specified file.

You can export and import session property configurations only between devices with identical model numbers, channel counts, and onboard memory sizes.

Related Topics:

Properties and Property Methods

Setting Properties Before Reading Properties

Note: You cannot call this method while the session is in a running state, such as while acquiring a signal.

Parameters

file_path (*str*) – Specifies the absolute path to the file containing the property configuration to import. If you specify an empty or relative path, this method returns an error. **Default File Extension:** .niscopeconfig

initiate

niscope.Session.initiate()

Initiates a waveform acquisition.

After calling this method, the digitizer leaves the Idle state and waits for a trigger. The digitizer acquires a waveform for each channel you enable with niscope. Session.configure_vertical().

Note: This method will return a Python context manager that will initiate on entering and abort on exit.

lock

niscope.Session.lock()

Obtains a multithread lock on the device session. Before doing so, the software waits until all other execution threads release their locks on the device session.

Other threads may have obtained a lock on this session for the following reasons:

- The application called the *niscope*. *Session*. *lock()* method.
- A call to NI-SCOPE locked the session.
- After a call to the *niscope*. Session.lock() method returns successfully, no other threads can access the device session until you call the *niscope*. Session.unlock() method or exit out of the with block when using lock context manager.
- Use the *niscope.Session.lock()* method and the *niscope.Session.unlock()* method around a sequence of calls to instrument driver methods if you require that the device retain its settings through the end of the sequence.

You can safely make nested calls to the *niscope.Session.lock()* method within the same thread. To completely unlock the session, you must balance each call to the *niscope.Session.lock()* method with a call to the *niscope.Session.unlock()* method.

One method for ensuring there are the same number of unlock method calls as there is lock calls is to use lock as a context manager

```
with niscope.Session('dev1') as session:
    with session.lock():
        # Calls to session within a single lock context
```

The first with block ensures the session is closed regardless of any exceptions raised

The second with block ensures that unlock is called regardless of any exceptions raised

Return type

context manager

Returns

When used in a *with* statement, *niscope.Session.lock()* acts as a context manager and unlock will be called when the *with* block is exited

probe compensation signal start

```
niscope.Session.probe_compensation_signal_start()
```

Starts the 1 kHz square wave output on PFI 1 for probe compensation.

probe_compensation_signal_stop

```
niscope.Session.probe_compensation_signal_stop()
```

Stops the 1 kHz square wave output on PFI 1 for probe compensation.

read

```
niscope.Session.read(num_samples=None, relative_to=niscope.FetchRelativeTo.PRETRIGGER, offset=0, record_number=0, num_records=None, timeout=hightime.timedelta(seconds=5.0))
```

Initiates an acquisition, waits for it to complete, and retrieves the data. The process is similar to calling niscope.Session._initiate_acquisition(), niscope.Session. acquisition_status(), and niscope.Session.fetch(). The only difference is that with niscope.Session.read(), you enable all channels specified with channelList before the acquisition; in the other method, you enable the channels with niscope.Session.configure_vertical().

This method may return multiple waveforms depending on the number of channels, the acquisition type, and the number of records you specify.

Note: Some functionality, such as time stamping, is not supported in all digitizers.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].read()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.read()

Parameters

- num_samples (int) The maximum number of samples to fetch for each waveform. If the acquisition finishes with fewer points than requested, some devices return partial data if the acquisition finished, was aborted, or a timeout of 0 was used. If it fails to complete within the timeout period, the method raises.
- relative_to (niscope.FetchRelativeTo) Position to start fetching within one record.
- **offset** (*int*) Offset in samples to start fetching data within each record. The offset can be positive or negative.
- **record_number** (*int*) Zero-based index of the first record to fetch.
- num_records (int) Number of records to fetch. Use -1 to fetch all configured records.
- timeout (hightime.timedelta, datetime.timedelta, or float in seconds) The time to wait for data to be acquired; using 0 for this parameter tells NI-SCOPE to fetch whatever is currently available. Using -1 seconds for this parameter implies infinite timeout.

Return type

list of WaveformInfo

Returns

Returns a list of class instances with the following timing and scaling information about each waveform:

- **relative_initial_x** (float) the time (in seconds) from the trigger to the first sample in the fetched waveform
- absolute_initial_x (float) timestamp (in seconds) of the first fetched sample. This timestamp is comparable between records and acquisitions; devices that do not support this parameter use 0 for this output.
- x_increment (float) the time between points in the acquired waveform in seconds
- channel (str) channel name this waveform was acquired from
- record (int) record number of this waveform
- gain (float) the gain factor of the given channel; useful for scaling binary data with the following formula:

voltage = binarydata * gainfactor + offset

• offset (float) the offset factor of the given channel; useful for scaling binary data with the following formula:

```
voltage = binarydata * gainfactor + offset
```

• samples (array of float) floating point array of samples. Length will be of the actual samples acquired

reset

```
niscope.Session.reset()
```

Stops the acquisition, releases routes, and all session properties are reset to their default states.

reset_device

```
niscope.Session.reset_device()
```

Performs a hard reset of the device. Acquisition stops, all routes are released, RTSI and PFI lines are tristated, hardware is configured to its default state, and all session properties are reset to their default state.

· Thermal Shutdown

reset_with_defaults

```
niscope.Session.reset_with_defaults()
```

Performs a software reset of the device, returning it to the default state and applying any initial default settings from the IVI Configuration Store.

self cal

niscope.Session.self_cal(option=niscope.Option.SELF_CALIBRATE_ALL_CHANNELS)

Self-calibrates most NI digitizers, including all SMC-based devices and most Traditional NI-DAQ (Legacy) devices. To verify that your digitizer supports self-calibration, refer to Features Supported by Device.

For SMC-based digitizers, if the self-calibration is performed successfully in a regular session, the calibration constants are immediately stored in the self-calibration area of the EEPROM. If the self-calibration is performed in an external calibration session, the calibration constants take effect immediately for the duration of the session. However, they are not stored in the EEPROM until niscope. Session.CalEnd() is called with action set to NISCOPE_VAL_ACTION_STORE and no errors occur.

Note: One or more of the referenced methods are not in the Python API for this driver.

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

Tip: This method can be called on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset, and then call this method on the result.

Example: my_session.channels[...].self_cal()

To call the method on all channels, you can call it directly on the niscope. Session.

Example: my_session.self_cal()

Parameters

option (niscope.Option) – The calibration option. Use VI_NULL for a normal self-calibration operation or NISCOPE_VAL_CAL_RESTORE_EXTERNAL_CALIBRATION to restore the previous calibration.

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

self test

niscope.Session.self_test()

Runs the instrument self-test routine and returns the test result(s). Refer to the device-specific help topics for an explanation of the message contents.

Raises SelfTestError on self test failure. Properties on exception object:

- code failure code from driver
- message status message from driver

Self-Test Code	Description
0	Passed self-test
1	Self-test failed

send_software_trigger_edge

niscope.Session.send_software_trigger_edge(which_trigger)

Sends the selected trigger to the digitizer. Call this method if you called <code>niscope.Session.configure_trigger_software()</code> when you want the Reference trigger to occur. You can also call this method to override a misused edge, digital, or hysteresis trigger. If you have configured <code>niscope.Session.acq_arm_source</code>, <code>niscope.Session.arm_ref_trig_src</code>, or <code>niscope.Session.adv_trig_src</code>, call this method when you want to send the corresponding trigger to the digitizer.

Parameters

 $\begin{tabular}{ll} \textbf{whichTrigger} (niscope. \textit{WhichTrigger}) - Specifies the type of trigger to send to the digitizer. \end{tabular}$

Defined Values

```
START (OL)

ARM_REFERENCE (1L)

REFERENCE (2L)

ADVANCE (3L)
```

unlock

niscope.Session.unlock()

Releases a lock that you acquired on an device session using *niscope*. Session.lock(). Refer to *niscope*. Session.unlock() for additional information on session locks.

Properties

absolute sample clock offset

niscope.Session.absolute_sample_clock_offset

Gets or sets the absolute time offset of the sample clock relative to the reference clock in terms of seconds.

Note: Configures the sample clock relationship with respect to the reference clock. This parameter is factored into NI-TClk adjustments and is typically used to improve the repeatability of NI-TClk Synchronization. When this parameter is read, the currently programmed value is returned. The range of the absolute sample clock offset is [-.5 sample clock periods, .5 sample clock periods]. The default absolute sample clock offset is 0s.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Clocking:Advanced:Absolute Sample Clock Offset
- C Attribute: NISCOPE_ATTR_ABSOLUTE_SAMPLE_CLOCK_OFFSET

acquisition start time

niscope.Session.acquisition_start_time

Specifies the length of time from the trigger event to the first point in the waveform record in seconds. If the value is positive, the first point in the waveform record occurs after the trigger event (same as specifying <code>niscope.Session.trigger_delay_time</code>). If the value is negative, the first point in the waveform record occurs before the trigger event (same as specifying <code>niscope.Session.horz_record_ref_position</code>).

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Horizontal:Advanced:Acquisition Start Time
- C Attribute: NISCOPE_ATTR_ACQUISITION_START_TIME

acquisition_type

niscope.Session.acquisition_type

Specifies how the digitizer acquires data and fills the waveform record.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.AcquisitionType
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Acquisition: Acquisition Type
- C Attribute: NISCOPE_ATTR_ACQUISITION_TYPE

acq arm source

niscope.Session.acq_arm_source

Specifies the source the digitizer monitors for a start (acquisition arm) trigger. When the start trigger is received, the digitizer begins acquiring pretrigger samples. Valid Values: NISCOPE_VAL_IMMEDIATE ('VAL_IMMEDIATE') - Triggers immediately NISCOPE_VAL_RTSI_0 ('VAL_RTSI_0') - RTSI 0 NISCOPE_VAL_RTSI_1 ('VAL_RTSI_1') - RTSI 1 NISCOPE_VAL_RTSI_2 ('VAL_RTSI_2') - RTSI 2 NISCOPE_VAL_RTSI_3 ('VAL_RTSI_3') - RTSI 3 NISCOPE_VAL_RTSI_4 ('VAL_RTSI_4') - RTSI 4 NISCOPE_VAL_RTSI_5 ('VAL_RTSI_5') - RTSI 5 NISCOPE_VAL_RTSI_6 ('VAL_RTSI_6') - RTSI 6 NISCOPE_VAL_PFI_0 ('VAL_PFI_0') - PFI 0 NISCOPE_VAL_PFI_1 ('VAL_PFI_1') - PFI 1 NISCOPE_VAL_PFI_2 ('VAL_PFI_2') - PFI 2 NISCOPE_VAL_PXI_STAR ('VAL_PXI_STAR') - PXI Star Trigger

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:Start Trigger (Acq. Arm):Source
- C Attribute: NISCOPE_ATTR_ACQ_ARM_SOURCE

advance_trigger_terminal_name

niscope.Session.advance_trigger_terminal_name

Returns the fully qualified name for the Advance Trigger terminal. You can use this terminal as the source for another trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Synchronization: Advance Trigger: Terminal Name
- C Attribute: NISCOPE_ATTR_ADVANCE_TRIGGER_TERMINAL_NAME

adv_trig_src

niscope.Session.adv_trig_src

Specifies the source the digitizer monitors for an advance trigger. When the advance trigger is received, the digitizer begins acquiring pretrigger samples.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Synchronization:Advance Trigger:Source

• C Attribute: NISCOPE_ATTR_ADV_TRIG_SRC

allow_more_records_than_memory

niscope.Session.allow_more_records_than_memory

Indicates whether more records can be configured with *niscope.Session.* configure_horizontal_timing() than fit in the onboard memory. If this property is set to True, it is necessary to fetch records while the acquisition is in progress. Eventually, some of the records will be overwritten. An error is returned from the fetch method if you attempt to fetch a record that has been overwritten.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Horizontal:Enable Records > Memory
- C Attribute: NISCOPE_ATTR_ALLOW_MORE_RECORDS_THAN_MEMORY

arm_ref_trig_src

niscope.Session.arm_ref_trig_src

Specifies the source the digitizer monitors for an arm reference trigger. When the arm reference trigger is received, the digitizer begins looking for a reference (stop) trigger from the user-configured trigger source.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization: Arm Reference Trigger: Source
- C Attribute: NISCOPE_ATTR_ARM_REF_TRIG_SRC

backlog

niscope.Session.backlog

Returns the number of samples (niscope.Session.points_done) that have been acquired but not fetched for the record specified by niscope.Session.fetch_record_number.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Fetch:Fetch Backlog
- C Attribute: NISCOPE_ATTR_BACKLOG

bandpass_filter_enabled

niscope.Session.bandpass_filter_enabled

Enables the bandpass filter on the specificed channel. The default value is FALSE.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].bandpass_filter_enabled

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.bandpass_filter_enabled

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Vertical:Advanced:Bandpass Filter Enabled
- C Attribute: NISCOPE_ATTR_BANDPASS_FILTER_ENABLED

binary_sample_width

niscope.Session.binary_sample_width

Indicates the bit width of the binary data in the acquired waveform. Useful for determining which Binary Fetch method to use. Compare to *niscope.Session.resolution*. To configure the device to store samples with a lower resolution that the native, set this property to the desired binary width. This can be useful for streaming at faster speeds at the cost of resolution. The least significant bits will be lost with this configuration. Valid Values: 8, 16, 32

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Acquisition:Binary Sample Width
- C Attribute: NISCOPE ATTR BINARY SAMPLE WIDTH

cable sense mode

niscope.Session.cable_sense_mode

Specifies whether and how the oscilloscope is configured to generate a CableSense signal on the specified channels when the niscope.Session.CableSenseSignalStart() method is called.

Device-Specific Behavior:

PXIe-5160/5162

- The value of this property must be identical across all channels whose input impedance is set to 50 ohms.
- If this property is set to a value other than *DISABLED* for any channel(s), the input impedance of all channels for which this property is set to *DISABLED* must be set to 1 M Ohm.

Supported Devices
PXIe-5110
PXIe-5111
PXIe-5113
PXIe-5160
PXIe-5162

Note: the input impedance of the channel(s) to convey the CableSense signal must be set to 50 ohms.

Note: One or more of the referenced methods are not in the Python API for this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.CableSenseMode
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_CABLE_SENSE_MODE

cable_sense_signal_enable

$\verb|niscope.Session.cable_sense_signal_enable|\\$

TBD

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_CABLE_SENSE_SIGNAL_ENABLE

cable_sense_voltage

niscope.Session.cable_sense_voltage

Returns the voltage of the CableSense signal that is written to the EEPROM of the oscilloscope during factory calibration.

Supported Devices
PXIe-5110
PXIe-5111
PXIe-5113
PXIe-5160
PXIe-5162

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_CABLE_SENSE_VOLTAGE

channel count

niscope.Session.channel_count

Indicates the number of channels that the specific instrument driver supports. For channel-based properties, the IVI engine maintains a separate cache value for each channel.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes:Driver Capabilities:Channel Count
- C Attribute: NISCOPE_ATTR_CHANNEL_COUNT

channel enabled

niscope.Session.channel_enabled

Specifies whether the digitizer acquires a waveform for the channel. Valid Values: True (1) - Acquire data on this channel False (0) - Don't acquire data on this channel

Tip: This property can be set/get on specific channels within your *niscope.Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].channel_enabled

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.channel_enabled

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Vertical: Channel Enabled
- C Attribute: NISCOPE_ATTR_CHANNEL_ENABLED

channel_terminal_configuration

niscope.Session.channel_terminal_configuration

Specifies the terminal configuration for the channel.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].channel_terminal_configuration

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.channel_terminal_configuration

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.TerminalConfiguration
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Vertical: Channel Terminal Configuration
- C Attribute: NISCOPE_ATTR_CHANNEL_TERMINAL_CONFIGURATION

data_transfer_block_size

niscope.Session.data_transfer_block_size

Specifies the maximum number of samples to transfer at one time from the device to host memory. Increasing this number should result in better fetching performance because the driver does not need to restart the transfers as often. However, increasing this number may also increase the amount of page-locked memory required from the system.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Fetch:Data Transfer Block Size
- C Attribute: NISCOPE_ATTR_DATA_TRANSFER_BLOCK_SIZE

data_transfer_maximum_bandwidth

niscope.Session.data_transfer_maximum_bandwidth

This property specifies the maximum bandwidth that the device is allowed to consume.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Fetch:Advanced:Maximum Bandwidth
- C Attribute: NISCOPE ATTR DATA TRANSFER MAXIMUM BANDWIDTH

data transfer preferred packet size

niscope.Session.data_transfer_preferred_packet_size

This property specifies the size of (read request|memory write) data payload. Due to alignment of the data buffers, the hardware may not always generate a packet of this size.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Fetch:Advanced:Preferred Packet Size
- C Attribute: NISCOPE_ATTR_DATA_TRANSFER_PREFERRED_PACKET_SIZE

device_temperature

niscope.Session.device_temperature

Returns the temperature of the device in degrees Celsius from the onboard sensor.

Tip: This property can be set/get on specific instruments within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container instruments to specify a subset.

Example: my_session.instruments[...].device_temperature

To set/get on all instruments, you can call the property directly on the *niscope*. Session.

Example: my_session.device_temperature

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	instruments

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: **Device:Temperature**

• C Attribute: NISCOPE_ATTR_DEVICE_TEMPERATURE

enabled channels

niscope.Session.enabled_channels

Returns a comma-separated list of the channels enabled for the session in ascending order.

If no channels are enabled, this property returns an empty string, "". If all channels are enabled, this property enumerates all of the channels.

Because this property returns channels in ascending order, but the order in which you specify channels for the input is important, the value of this property may not necessarily reflect the order in which NI-SCOPE performs certain actions.

Refer to Channel String Syntax in the NI High-Speed Digitizers Help for more information on the effects of channel order in NI-SCOPE.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_ENABLED_CHANNELS

enable dc restore

niscope.Session.enable_dc_restore

Restores the video-triggered data retrieved by the digitizer to the video signal's zero reference point. Valid Values: True - Enable DC restore False - Disable DC restore

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Trigger Video:Enable DC Restore
- C Attribute: NISCOPE_ATTR_ENABLE_DC_RESTORE

enable time interleaved sampling

niscope.Session.enable_time_interleaved_sampling

Specifies whether the digitizer acquires the waveform using multiple ADCs for the channel enabling a higher maximum real-time sampling rate. Valid Values: True (1) - Use multiple interleaved ADCs on this channel False (0) - Use only this channel's ADC to acquire data for this channel

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].enable_time_interleaved_sampling

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.enable_time_interleaved_sampling

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Horizontal:Enable Time Interleaved Sampling
- C Attribute: NISCOPE_ATTR_ENABLE_TIME_INTERLEAVED_SAMPLING

end of acquisition event output terminal

niscope.Session.end_of_acquisition_event_output_terminal

Specifies the destination for the End of Acquisition Event. When this event is asserted, the digitizer has completed sampling for all records. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:End of Acquisition:Output Terminal
- C Attribute: NISCOPE_ATTR_END_OF_ACQUISITION_EVENT_OUTPUT_TERMINAL

end_of_acquisition_event_terminal_name

niscope.Session.end_of_acquisition_event_terminal_name

Returns the fully qualified name for the End of Acquisition Event terminal. You can use this terminal as the source for a trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Synchronization: End of Acquisition: Terminal Name
- C Attribute: NISCOPE_ATTR_END_OF_ACQUISITION_EVENT_TERMINAL_NAME

end of record event output terminal

niscope.Session.end_of_record_event_output_terminal

Specifies the destination for the End of Record Event. When this event is asserted, the digitizer has completed sampling for the current record. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:End of Record:Output Terminal
- C Attribute: NISCOPE_ATTR_END_OF_RECORD_EVENT_OUTPUT_TERMINAL

end_of_record_event_terminal_name

niscope.Session.end_of_record_event_terminal_name

Returns the fully qualified name for the End of Record Event terminal. You can use this terminal as the source for a trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Synchronization: End of Record: Terminal Name
- C Attribute: NISCOPE_ATTR_END_OF_RECORD_EVENT_TERMINAL_NAME

end_of_record_to_advance_trigger_holdoff

niscope.Session.end_of_record_to_advance_trigger_holdoff

End of Record to Advance Trigger Holdoff is the length of time (in seconds) that a device waits between the completion of one record and the acquisition of pre-trigger samples for the next record. During this time, the acquisition engine state delays the transition to the Wait for Advance Trigger state, and will not store samples in onboard memory, accept an Advance Trigger, or trigger on the input signal.. **Supported Devices**: NI 5185/5186

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:End of Record to Advance Trigger Holdoff
- C Attribute: NISCOPE_ATTR_END_OF_RECORD_TO_ADVANCE_TRIGGER_HOLDOFF

equalization filter enabled

niscope.Session.equalization_filter_enabled

Enables the onboard signal processing FIR block. This block is connected directly to the input signal. This filter is designed to compensate the input signal for artifacts introduced to the signal outside of the digitizer. However, since this is a generic FIR filter any coefficients are valid. Coefficients should be between +1 and -1 in value.

Tip: This property can be set/get on specific channels within your *niscope.Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].equalization_filter_enabled

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.equalization_filter_enabled

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Onboard Signal Processing: Equalization: Equalization Filter Enabled

• C Attribute: NISCOPE ATTR EQUALIZATION FILTER ENABLED

equalization num coefficients

niscope.Session.equalization_num_coefficients

Returns the number of coefficients that the FIR filter can accept. This filter is designed to compensate the input signal for artifacts introduced to the signal outside of the digitizer. However, since this is a generic FIR filter any coefficients are valid. Coefficients should be between +1 and -1 in value.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].equalization_num_coefficients

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.equalization_num_coefficients

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Onboard Signal Processing: Equalization: Equalization Num Coefficients
- C Attribute: NISCOPE ATTR EQUALIZATION NUM COEFFICIENTS

exported_advance_trigger_output_terminal

niscope.Session.exported_advance_trigger_output_terminal

Specifies the destination to export the advance trigger. When the advance trigger is received, the digitizer begins acquiring samples for the Nth record. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Synchronization:Advance Trigger:Output Terminal
- C Attribute: NISCOPE_ATTR_EXPORTED_ADVANCE_TRIGGER_OUTPUT_TERMINAL

exported_ref_trigger_output_terminal

niscope.Session.exported_ref_trigger_output_terminal

Specifies the destination export for the reference (stop) trigger. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Trigger Output Terminal
- C Attribute: NISCOPE_ATTR_EXPORTED_REF_TRIGGER_OUTPUT_TERMINAL

exported_start_trigger_output_terminal

niscope.Session.exported_start_trigger_output_terminal

Specifies the destination to export the Start trigger. When the start trigger is received, the digitizer begins acquiring samples. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Synchronization:Start Trigger (Acq. Arm):Output Terminal
- $\bullet \ \ C \ Attribute: \ \textbf{NISCOPE_ATTR_EXPORTED_START_TRIGGER_OUTPUT_TERMINAL}$

flex fir antialias filter type

niscope.Session.flex_fir_antialias_filter_type

The NI 5922 flexible-resolution digitizer uses an onboard FIR lowpass antialias filter. Use this property to select from several types of filters to achieve desired filtering characteristics.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].flex_fir_antialias_filter_type

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.flex_fir_antialias_filter_type

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.FlexFIRAntialiasFilterType
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Vertical:Advanced:Flex FIR Antialias Filter Type
- C Attribute: NISCOPE_ATTR_FLEX_FIR_ANTIALIAS_FILTER_TYPE

fpga bitfile path

niscope.Session.fpga_bitfile_path

Gets the absolute file path to the bitfile loaded on the FPGA.

Note: Gets the absolute file path to the bitfile loaded on the FPGA.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Device:FPGA Bitfile Path
- C Attribute: NISCOPE_ATTR_FPGA_BITFILE_PATH

glitch_condition

niscope.Session.glitch_condition

Specifies whether the oscilloscope triggers on pulses of duration less than or greater than the value specified by the *niscope*. Session. *glitch_width* property.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.GlitchCondition
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_GLITCH_CONDITION

glitch_polarity

niscope.Session.glitch_polarity

Specifies the polarity of pulses that trigger the oscilloscope for glitch triggering.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.GlitchPolarity
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_GLITCH_POLARITY

glitch_width

niscope.Session.glitch_width

Specifies the glitch duration, in seconds.

The oscilloscope triggers when it detects of pulse of duration either less than or greater than this value depending on the value of the *niscope*. Session. glitch_condition property.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_GLITCH_WIDTH

high_pass_filter_frequency

niscope.Session.high_pass_filter_frequency

Specifies the frequency for the highpass filter in Hz. The device uses one of the valid values listed below. If an invalid value is specified, no coercion occurs. The default value is 0. (**PXIe-5164**) **Valid Values:** 0 90 450 **Related topics:** Digital Filtering

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].high_pass_filter_frequency

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.high_pass_filter_frequency

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Vertical:Advanced:High Pass Filter Frequency
- C Attribute: NISCOPE_ATTR_HIGH_PASS_FILTER_FREQUENCY

horz_enforce_realtime

niscope.Session.horz_enforce_realtime

Indicates whether the digitizer enforces real-time measurements or allows equivalent-time measurements.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Horizontal:Enforce Realtime

• C Attribute: NISCOPE_ATTR_HORZ_ENFORCE_REALTIME

horz_min_num_pts

niscope.Session.horz_min_num_pts

Specifies the minimum number of points you require in the waveform record for each channel. NI-SCOPE uses the value you specify to configure the record length that the digitizer uses for waveform acquisition. $niscope.Session.horz_record_length$ returns the actual record length. Valid Values: 1 - available onboard memory

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Horizontal:Min Number of Points

• C Attribute: NISCOPE_ATTR_HORZ_MIN_NUM_PTS

horz num records

niscope.Session.horz_num_records

Specifies the number of records to acquire. Can be used for multi-record acquisition and single-record acquisitions. Setting this to 1 indicates a single-record acquisition.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Horizontal:Number of Records

• C Attribute: NISCOPE_ATTR_HORZ_NUM_RECORDS

horz_record_length

niscope.Session.horz_record_length

Returns the actual number of points the digitizer acquires for each channel. The value is equal to or greater than the minimum number of points you specify with <code>niscope.Session.horz_min_num_pts</code>. Allocate a ViReal64 array of this size or greater to pass as the WaveformArray parameter of the Read and Fetch methods. This property is only valid after a call to the one of the Configure Horizontal methods.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Horizontal:Actual Record Length
- C Attribute: NISCOPE_ATTR_HORZ_RECORD_LENGTH

horz record ref position

niscope.Session.horz_record_ref_position

Specifies the position of the Reference Event in the waveform record. When the digitizer detects a trigger, it waits the length of time the <code>niscope.Session.trigger_delay_time</code> property specifies. The event that occurs when the delay time elapses is the Reference Event. The Reference Event is relative to the start of the record and is a percentage of the record length. For example, the value 50.0 corresponds to the center of the waveform record and 0.0 corresponds to the first element in the waveform record. Valid Values: 0.0 - 100.0

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Horizontal:Reference Position
- C Attribute: NISCOPE_ATTR_HORZ_RECORD_REF_POSITION

horz sample rate

niscope.Session.horz_sample_rate

Returns the effective sample rate using the current configuration. The units are samples per second. This property is only valid after a call to the one of the Configure Horizontal methods. Units: Hertz (Samples / Second)

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Horizontal:Actual Sample Rate
- C Attribute: NISCOPE_ATTR_HORZ_SAMPLE_RATE

horz time per record

niscope.Session.horz_time_per_record

Specifies the length of time that corresponds to the record length. Units: Seconds

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Horizontal:Advanced:Time Per Record
- C Attribute: NISCOPE_ATTR_HORZ_TIME_PER_RECORD

input clock source

niscope.Session.input_clock_source

Specifies the input source for the PLL reference clock (the 1 MHz to 20 MHz clock on the NI 5122, the 10 MHz clock for the NI 5112/5620/5621/5911) to which the digitizer will be phase-locked; for the NI 5102, this is the source of the board clock.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Clocking:Reference (Input) Clock Source

• C Attribute: NISCOPE_ATTR_INPUT_CLOCK_SOURCE

input_impedance

niscope.Session.input_impedance

Specifies the input impedance for the channel in Ohms.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].input_impedance

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.input_impedance

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Vertical:Input Impedance

• C Attribute: NISCOPE_ATTR_INPUT_IMPEDANCE

instrument_firmware_revision

niscope.Session.instrument_firmware_revision

A string that contains the firmware revision information for the instrument you are currently using.

Tip: This property can be set/get on specific instruments within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container instruments to specify a subset.

Example: my_session.instruments[...].instrument_firmware_revision

To set/get on all instruments, you can call the property directly on the niscope. Session.

Example: my_session.instrument_firmware_revision

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	instruments

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes:Instrument Identification:Firmware Revision
- C Attribute: NISCOPE_ATTR_INSTRUMENT_FIRMWARE_REVISION

instrument manufacturer

niscope.Session.instrument_manufacturer

A string that contains the name of the instrument manufacturer.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Inherent IVI Attributes:Instrument Identification:Manufacturer
- C Attribute: NISCOPE_ATTR_INSTRUMENT_MANUFACTURER

instrument model

niscope.Session.instrument_model

A string that contains the model number of the current instrument.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes:Instrument Identification:Model
- C Attribute: NISCOPE_ATTR_INSTRUMENT_MODEL

interleaving offset correction enabled

niscope.Session.interleaving_offset_correction_enabled

Enables the interleaving offset correction on the specified channel. The default value is TRUE. **Related topics:** Timed Interleaved Sampling

Note: If disabled, warranted specifications are not guaranteed.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].interleaving_offset_correction_enabled

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.interleaving_offset_correction_enabled

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Vertical:Advanced:Interleaving Offset Correction Enabled
- C Attribute: NISCOPE_ATTR_INTERLEAVING_OFFSET_CORRECTION_ENABLED

io_resource_descriptor

niscope.Session.io_resource_descriptor

Indicates the resource descriptor the driver uses to identify the physical device. If you initialize the driver with a logical name, this property contains the resource descriptor that corresponds to the entry in the IVI Configuration utility. If you initialize the instrument driver with the resource descriptor, this property contains that value. You can pass a logical name to niscope. Session. Init() or niscope. Session. __init__(). The IVI Configuration utility must contain an entry for the logical name. The logical name entry refers to a virtual instrument section in the IVI Configuration file. The virtual instrument section specifies a physical device and initial user options.

Note: One or more of the referenced methods are not in the Python API for this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes:Advanced Session Information:Resource Descriptor
- C Attribute: NISCOPE ATTR IO RESOURCE DESCRIPTOR

is_probe_comp_on

niscope.Session.is_probe_comp_on

Tip: This property can be set/get on specific instruments within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container instruments to specify a subset.

Example: my_session.instruments[...].is_probe_comp_on

To set/get on all instruments, you can call the property directly on the niscope. Session.

Example: my_session.is_probe_comp_on

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read only
Repeated Capabilities	instruments

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

C Attribute: NISCOPE_ATTR_IS_PROBE_COMP_ON

logical_name

niscope.Session.logical_name

A string containing the logical name you specified when opening the current IVI session. You can pass a logical name to niscope.Session.Init() or niscope.Session.__init__(). The IVI Configuration utility must contain an entry for the logical name. The logical name entry refers to a virtual instrument section in the IVI Configuration file. The virtual instrument section specifies a physical device and initial user options.

Note: One or more of the referenced methods are not in the Python API for this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes: Advanced Session Information: Logical Name
- C Attribute: NISCOPE_ATTR_LOGICAL_NAME

master_enable

niscope.Session.master_enable

Specifies whether you want the device to be a master or a slave. The master typically originates the trigger signal and clock sync pulse. For a standalone device, set this property to False.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Synchronization:Master Enable
- C Attribute: NISCOPE_ATTR_MASTER_ENABLE

max input frequency

niscope.Session.max_input_frequency

Specifies the bandwidth of the channel. Express this value as the frequency at which the input circuitry attenuates the input signal by 3 dB. The units are hertz. Defined Values: NISCOPE_VAL_BANDWIDTH_FULL (-1.0) NISCOPE_VAL_BANDWIDTH_DEVICE_DEFAULT (0.0) NISCOPE_VAL_20MHZ_BANDWIDTH (20000000.0) NISCOPE_VAL_100MHZ_BANDWIDTH (1000000000.0) NISCOPE_VAL_20MHZ_MAX_INPUT_FREQUENCY (20000000.0) NISCOPE_VAL_100MHZ_MAX_INPUT_FREQUENCY (1000000000.0)

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].max_input_frequency

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.max_input_frequency

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Vertical:Maximum Input Frequency
- C Attribute: NISCOPE_ATTR_MAX_INPUT_FREQUENCY

max real time sampling rate

niscope.Session.max_real_time_sampling_rate

Returns the maximum real time sample rate in Hz.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Horizontal:Maximum Real Time Sample Rate
- C Attribute: NISCOPE_ATTR_MAX_REAL_TIME_SAMPLING_RATE

max_ris_rate

niscope.Session.max_ris_rate

Returns the maximum sample rate in RIS mode in Hz.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Horizontal:Maximum RIS Rate
- C Attribute: NISCOPE_ATTR_MAX_RIS_RATE

meas_array_gain

niscope.Session.meas_array_gain

Every element of an array is multiplied by this scalar value during the Array Gain measurement. Refer to ARRAY_GAIN for more information. Default: 1.0

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_array_gain

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_array_gain

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement: Array Gain
- C Attribute: NISCOPE_ATTR_MEAS_ARRAY_GAIN

meas_array_offset

niscope.Session.meas_array_offset

Every element of an array is added to this scalar value during the Array Offset measurement. Refer to ARRAY_OFFSET for more information. Default: 0.0

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_array_offset

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_array_offset

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Array Offset
- C Attribute: NISCOPE_ATTR_MEAS_ARRAY_OFFSET

meas_chan_high_ref_level

niscope.Session.meas_chan_high_ref_level

Stores the high reference level used in many scalar measurements. Different channels may have different reference levels. Do not use the IVI-defined, nonchannel-based properties such as <code>niscope.Session.meas_high_ref</code> if you use this property to set various channels to different values. Default: 90%

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_chan_high_ref_level

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_chan_high_ref_level

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Reference Levels:Channel Based High Ref Level
- C Attribute: NISCOPE_ATTR_MEAS_CHAN_HIGH_REF_LEVEL

meas chan low ref level

niscope.Session.meas_chan_low_ref_level

Stores the low reference level used in many scalar measurements. Different channels may have different reference levels. Do not use the IVI-defined, nonchannel-based properties such as <code>niscope.Session.meas_low_ref</code> if you use this property to set various channels to different values. Default: 10%

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_chan_low_ref_level

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_chan_low_ref_level

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Reference Levels:Channel Based Low Ref Level
- C Attribute: NISCOPE_ATTR_MEAS_CHAN_LOW_REF_LEVEL

meas_chan_mid_ref_level

niscope.Session.meas_chan_mid_ref_level

Stores the mid reference level used in many scalar measurements. Different channels may have different reference levels. Do not use the IVI-defined, nonchannel-based properties such as <code>niscope.Session.meas_mid_ref</code> if you use this property to set various channels to different values. Default: 50%

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_chan_mid_ref_level

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_chan_mid_ref_level

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Reference Levels:Channel Based Mid Ref Level
- C Attribute: NISCOPE_ATTR_MEAS_CHAN_MID_REF_LEVEL

meas_filter_center_freq

niscope.Session.meas_filter_center_freq

The center frequency in hertz for filters of type bandpass and bandstop. The width of the filter is specified by $niscope.Session.meas_filter_width$, where the cutoff frequencies are the center \pm width. Default: 1.0e6 Hz

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_center_freq

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_center_freq

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Filter:Center Frequency
- C Attribute: NISCOPE_ATTR_MEAS_FILTER_CENTER_FREQ

meas_filter_cutoff_freq

niscope.Session.meas_filter_cutoff_freq

Specifies the cutoff frequency in hertz for filters of type lowpass and highpass. The cutoff frequency definition varies depending on the filter. Default: 1.0e6 Hz

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_cutoff_freq

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_cutoff_freq

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Filter:Cutoff Frequency
- C Attribute: NISCOPE_ATTR_MEAS_FILTER_CUTOFF_FREQ

meas filter order

niscope.Session.meas_filter_order

Specifies the order of an IIR filter. All positive integers are valid. Default: 2

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_order

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_order

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Filter:IIR Order
- C Attribute: NISCOPE_ATTR_MEAS_FILTER_ORDER

meas_filter_ripple

niscope.Session.meas_filter_ripple

Specifies the amount of ripple in the passband in units of decibels (positive values). Used only for Chebyshev filters. The more ripple allowed gives a sharper cutoff for a given filter order. Default: 0.1 dB

Tip: This property can be set/get on specific channels within your *niscope.Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_ripple

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_ripple

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Filter:Ripple
- C Attribute: NISCOPE ATTR MEAS FILTER RIPPLE

meas filter taps

niscope.Session.meas_filter_taps

Defines the number of taps (coefficients) for an FIR filter. Default: 25

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_taps

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_taps

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Filter:FIR Taps
- C Attribute: NISCOPE_ATTR_MEAS_FILTER_TAPS

meas_filter_transient_waveform_percent

niscope.Session.meas_filter_transient_waveform_percent

The percentage (0 - 100%) of the IIR filtered waveform to eliminate from the beginning of the waveform. This allows eliminating the transient portion of the waveform that is undefined due to the assumptions necessary at the boundary condition. Default: 20.0%

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_transient_waveform_percent

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_transient_waveform_percent

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Filter:Percent Waveform Transient
- C Attribute: NISCOPE_ATTR_MEAS_FILTER_TRANSIENT_WAVEFORM_PERCENT

meas filter type

niscope.Session.meas_filter_type

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_type

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_filter_type

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.FilterType
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Filter:Type
- C Attribute: NISCOPE ATTR MEAS FILTER TYPE

meas_filter_width

niscope.Session.meas_filter_width

Specifies the width of bandpass and bandstop type filters in hertz. The cutoff frequencies occur at $niscope.Session.meas_filter_center_freq \pm one-half width$. Default: 1.0e3 Hz

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_filter_width

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_filter_width

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Filter:Width
- C Attribute: NISCOPE_ATTR_MEAS_FILTER_WIDTH

meas fir filter window

niscope.Session.meas_fir_filter_window

Specifies the FIR window type. The possible choices are: NONE HANNING_WINDOW HAMMING_WINDOW TRIANGLE_WINDOW FLAT_TOP_WINDOW BLACKMAN_WINDOW The symmetric windows are applied to the FIR filter coefficients to limit passband ripple in FIR filters. Default: NONE

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_fir_filter_window

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_fir_filter_window

Characteristic	Value
Datatype	enums.FIRFilterWindow
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Filter:FIR Window
- C Attribute: NISCOPE_ATTR_MEAS_FIR_FILTER_WINDOW

meas_high_ref

niscope.Session.meas_high_ref

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_MEAS_HIGH_REF

meas_hysteresis_percent

niscope.Session.meas_hysteresis_percent

Digital hysteresis that is used in several of the scalar waveform measurements. This property specifies the percentage of the full-scale vertical range for the hysteresis window size. Default: 2%

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_hysteresis_percent

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_hysteresis_percent

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement: Hysteresis Percent
- C Attribute: NISCOPE ATTR MEAS HYSTERESIS PERCENT

meas_interpolation_sampling_factor

niscope.Session.meas_interpolation_sampling_factor

The new number of points for polynomial interpolation is the sampling factor times the input number of points. For example, if you acquire 1,000 points with the digitizer and set this property to 2.5, calling niscope. Session. FetchWaveformMeasurementArray() with the POLYNOMIAL_INTERPOLATION measurement resamples the waveform to 2,500 points. Default: 2.0

Note: One or more of the referenced methods are not in the Python API for this driver.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_interpolation_sampling_factor

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_interpolation_sampling_factor

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Interpolation:Sampling Factor
- C Attribute: NISCOPE ATTR MEAS INTERPOLATION SAMPLING FACTOR

meas_last_acq_histogram_size

niscope.Session.meas_last_acq_histogram_size

Specifies the size (that is, the number of bins) in the last acquisition histogram. This histogram is used to determine several scalar measurements, most importantly voltage low and voltage high. Default: 256

Tip: This property can be set/get on specific channels within your *niscope.Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_last_acq_histogram_size

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_last_acq_histogram_size

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Last Acq. Histogram Size
- C Attribute: NISCOPE ATTR MEAS LAST ACQ HISTOGRAM SIZE

meas_low_ref

niscope.Session.meas_low_ref

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_MEAS_LOW_REF

meas_mid_ref

niscope.Session.meas_mid_ref

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

• C Attribute: NISCOPE ATTR MEAS MID REF

meas_other_channel

niscope.Session.meas_other_channel

Specifies the second channel for two-channel measurements, such as *ADD_CHANNELS*. If processing steps are registered with this channel, the processing is done before the waveform is used in a two-channel measurement. Default: '0'

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_other_channel

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_other_channel

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str or int
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Other Channel
- C Attribute: NISCOPE_ATTR_MEAS_OTHER_CHANNEL

meas percentage method

niscope.Session.meas_percentage_method

Specifies the method used to map percentage reference units to voltages for the reference. Possible values are: NISCOPE_VAL_MEAS_LOW_HIGH NISCOPE_VAL_MEAS_MIN_MAX NISCOPE_VAL_MEAS_BASE_TOP Default: NISCOPE_VAL_MEAS_BASE_TOP

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_percentage_method

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_percentage_method

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.PercentageMethod
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Reference Levels:Percentage Units Method
- C Attribute: NISCOPE_ATTR_MEAS_PERCENTAGE_METHOD

meas_polynomial_interpolation_order

niscope.Session.meas_polynomial_interpolation_order

Specifies the polynomial order used for the polynomial interpolation measurement. For example, an order of 1 is linear interpolation whereas an order of 2 specifies parabolic interpolation. Any positive integer is valid. Default: 1

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_polynomial_interpolation_order

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_polynomial_interpolation_order

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Interpolation:Polynomial Interpolation Order
- C Attribute: NISCOPE_ATTR_MEAS_POLYNOMIAL_INTERPOLATION_ORDER

meas ref level units

niscope.Session.meas_ref_level_units

Specifies the units of the reference levels. NISCOPE_VAL_MEAS_VOLTAGE—Specifies that the reference levels are given in units of volts NISCOPE_VAL_MEAS_PERCENTAGE—Percentage units, where the measurements voltage low and voltage high represent 0% and 100%, respectively. Default: NISCOPE_VAL_MEAS_PERCENTAGE

Note: One or more of the referenced values are not in the Python API for this driver. Enums that only define values, or represent True/False, have been removed.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_ref_level_units

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_ref_level_units

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.RefLevelUnits
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Reference Levels:Units
- C Attribute: NISCOPE_ATTR_MEAS_REF_LEVEL_UNITS

meas time histogram high time

niscope.Session.meas_time_histogram_high_time

Specifies the highest time value included in the multiple acquisition time histogram. The units are always seconds. Default: 5.0e-4 seconds

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_time_histogram_high_time

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_time_histogram_high_time

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Time Histogram:High Time
- C Attribute: NISCOPE_ATTR_MEAS_TIME_HISTOGRAM_HIGH_TIME

meas_time_histogram_high_volts

niscope.Session.meas_time_histogram_high_volts

Specifies the highest voltage value included in the multiple-acquisition time histogram. The units are always volts. Default: $10.0~\rm V$

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_time_histogram_high_volts

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_time_histogram_high_volts

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Time Histogram:High Volts
- C Attribute: NISCOPE_ATTR_MEAS_TIME_HISTOGRAM_HIGH_VOLTS

meas_time_histogram_low_time

niscope.Session.meas_time_histogram_low_time

Specifies the lowest time value included in the multiple-acquisition time histogram. The units are always seconds. Default: -5.0e-4 seconds

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_time_histogram_low_time

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_time_histogram_low_time

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement: Time Histogram: Low Time
- C Attribute: NISCOPE_ATTR_MEAS_TIME_HISTOGRAM_LOW_TIME

meas time histogram low volts

niscope.Session.meas_time_histogram_low_volts

Specifies the lowest voltage value included in the multiple acquisition time histogram. The units are always volts. Default: $-10.0~\rm V$

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_time_histogram_low_volts

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_time_histogram_low_volts

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Time Histogram:Low Volts
- C Attribute: NISCOPE_ATTR_MEAS_TIME_HISTOGRAM_LOW_VOLTS

meas time histogram size

niscope.Session.meas_time_histogram_size

Determines the multiple acquisition voltage histogram size. The size is set during the first call to a time histogram measurement after clearing the measurement history with niscope. Session. clear_waveform_measurement_stats(). Default: 256

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_time_histogram_size

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_time_histogram_size

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Time Histogram:Size
- $\bullet \ \ C \ Attribute: \ \textbf{NISCOPE_ATTR_MEAS_TIME_HISTOGRAM_SIZE}$

meas voltage histogram high volts

niscope.Session.meas_voltage_histogram_high_volts

Specifies the highest voltage value included in the multiple acquisition voltage histogram. The units are always volts. Default: $10.0~\rm V$

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_voltage_histogram_high_volts

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_voltage_histogram_high_volts

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement:Voltage Histogram:High Volts
- C Attribute: NISCOPE_ATTR_MEAS_VOLTAGE_HISTOGRAM_HIGH_VOLTS

meas voltage histogram low volts

niscope.Session.meas_voltage_histogram_low_volts

Specifies the lowest voltage value included in the multiple-acquisition voltage histogram. The units are always volts. Default: $-10.0~\rm V$

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_voltage_histogram_low_volts

To set/get on all channels, you can call the property directly on the *niscope*. Session.

Example: my_session.meas_voltage_histogram_low_volts

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

- LabVIEW Property: Waveform Measurement:Voltage Histogram:Low Volts
- C Attribute: NISCOPE_ATTR_MEAS_VOLTAGE_HISTOGRAM_LOW_VOLTS

meas_voltage_histogram_size

niscope.Session.meas_voltage_histogram_size

Determines the multiple acquisition voltage histogram size. The size is set the first time a voltage histogram measurement is called after clearing the measurement history with the method *niscope*. Session.clear_waveform_measurement_stats(). Default: 256

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].meas_voltage_histogram_size

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.meas_voltage_histogram_size

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Waveform Measurement: Voltage Histogram: Size
- C Attribute: NISCOPE_ATTR_MEAS_VOLTAGE_HISTOGRAM_SIZE

min_sample_rate

niscope.Session.min_sample_rate

Specify the sampling rate for the acquisition in Samples per second. Valid Values: The combination of sampling rate and min record length must allow the digitizer to sample at a valid sampling rate for the acquisition type specified in niscope.Session.ConfigureAcquisition() and not require more memory than the onboard memory module allows.

Note: One or more of the referenced methods are not in the Python API for this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

• LabVIEW Property: Horizontal:Min Sample Rate

• C Attribute: NISCOPE_ATTR_MIN_SAMPLE_RATE

onboard_memory_size

niscope.Session.onboard_memory_size

Returns the total combined amount of onboard memory for all channels in bytes.

Tip: This property can be set/get on specific instruments within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container instruments to specify a subset.

Example: my_session.instruments[...].onboard_memory_size

To set/get on all instruments, you can call the property directly on the niscope. Session.

Example: my_session.onboard_memory_size

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	instruments

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Horizontal:Memory Size

• C Attribute: NISCOPE_ATTR_ONBOARD_MEMORY_SIZE

output clock source

niscope.Session.output_clock_source

Specifies the output source for the 10 MHz clock to which another digitizer's sample clock can be phased-locked.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

LabVIEW Property: Clocking:Output Clock Source

• C Attribute: NISCOPE_ATTR_OUTPUT_CLOCK_SOURCE

pll_lock_status

niscope.Session.pll_lock_status

If TRUE, the PLL has remained locked to the external reference clock since it was last checked. If FALSE, the PLL has become unlocked from the external reference clock since it was last checked.

Tip: This property can be set/get on specific instruments within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container instruments to specify a subset.

Example: my_session.instruments[...].pll_lock_status

To set/get on all instruments, you can call the property directly on the niscope. Session.

Example: my_session.pll_lock_status

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read only
Repeated Capabilities	instruments

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Clocking:PLL Lock Status

• C Attribute: NISCOPE_ATTR_PLL_LOCK_STATUS

points done

niscope.Session.points_done

Actual number of samples acquired in the record specified by niscope. Session. fetch_record_number from the niscope. Session.fetch_relative_to and niscope. Session.fetch_offset properties.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Fetch:Points Done

• C Attribute: NISCOPE ATTR POINTS DONE

poll interval

niscope.Session.poll_interval

Specifies the poll interval in milliseconds to use during RIS acquisitions to check whether the acquisition is complete.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_POLL_INTERVAL

probe attenuation

niscope.Session.probe_attenuation

Specifies the probe attenuation for the input channel. For example, for a 10:1 probe, set this property to 10.0. Valid Values: Any positive real number. Typical values are 1, 10, and 100.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].probe_attenuation

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.probe_attenuation

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Vertical:Probe Attenuation

• C Attribute: NISCOPE_ATTR_PROBE_ATTENUATION

ready_for_advance_event_output_terminal

niscope.Session.ready_for_advance_event_output_terminal

Specifies the destination for the Ready for Advance Event. When this event is asserted, the digitizer is ready to receive an advance trigger. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:Ready for Advance:Output Terminal
- C Attribute: NISCOPE_ATTR_READY_FOR_ADVANCE_EVENT_OUTPUT_TERMINAL

ready_for_advance_event_terminal_name

niscope.Session.ready_for_advance_event_terminal_name

Returns the fully qualified name for the Ready for Advance Event terminal. You can use this terminal as the source for a trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Synchronization:Ready for Advance:Terminal Name
- C Attribute: NISCOPE_ATTR_READY_FOR_ADVANCE_EVENT_TERMINAL_NAME

ready for ref event output terminal

niscope.Session.ready_for_ref_event_output_terminal

Specifies the destination for the Ready for Reference Event. When this event is asserted, the digitizer is ready to receive a reference trigger. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:Ready for Reference:Output Terminal
- C Attribute: NISCOPE_ATTR_READY_FOR_REF_EVENT_OUTPUT_TERMINAL

ready_for_ref_event_terminal_name

niscope.Session.ready_for_ref_event_terminal_name

Returns the fully qualified name for the Ready for Reference Event terminal. You can use this terminal as the source for a trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Synchronization: Ready for Reference: Terminal Name
- C Attribute: NISCOPE_ATTR_READY_FOR_REF_EVENT_TERMINAL_NAME

ready_for_start_event_output_terminal

niscope.Session.ready_for_start_event_output_terminal

Specifies the destination for the Ready for Start Event. When this event is asserted, the digitizer is ready to receive a start trigger. Consult your device documentation for a specific list of valid destinations.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:Ready for Start:Output Terminal
- C Attribute: NISCOPE_ATTR_READY_FOR_START_EVENT_OUTPUT_TERMINAL

ready_for_start_event_terminal_name

niscope.Session.ready_for_start_event_terminal_name

Returns the fully qualified name for the Ready for Start Event terminal. You can use this terminal as the source for a trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Synchronization: Ready for Start: Terminal Name
- C Attribute: NISCOPE_ATTR_READY_FOR_START_EVENT_TERMINAL_NAME

records done

niscope.Session.records_done

Specifies the number of records that have been completely acquired.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Fetch:Records Done

• C Attribute: NISCOPE_ATTR_RECORDS_DONE

record_arm_source

niscope.Session.record_arm_source

Specifies the record arm source.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:Record Arm Source
- C Attribute: NISCOPE_ATTR_RECORD_ARM_SOURCE

ref_clk_rate

niscope.Session.ref_clk_rate

If <code>niscope.Session.input_clock_source</code> is an external source, this property specifies the frequency of the input, or reference clock, to which the internal sample clock timebase is synchronized. The frequency is in hertz.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

• LabVIEW Property: Clocking:Reference Clock Rate

• C Attribute: NISCOPE_ATTR_REF_CLK_RATE

ref_trigger_detector_location

niscope.Session.ref_trigger_detector_location

Indicates which analog compare circuitry to use on the device.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.RefTriggerDetectorLocation
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Onboard Signal Processing:Ref Trigger Detection Location
- C Attribute: NISCOPE ATTR REF TRIGGER DETECTOR LOCATION

ref_trigger_minimum_quiet_time

niscope.Session.ref_trigger_minimum_quiet_time

The amount of time the trigger circuit must not detect a signal above the trigger level before the trigger is armed. This property is useful for triggering at the beginning and not in the middle of signal bursts.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Triggering:Onboard Signal Processing:Ref Trigger Min Quiet Time
- C Attribute: NISCOPE_ATTR_REF_TRIGGER_MINIMUM_QUIET_TIME

ref_trigger_terminal_name

niscope.Session.ref_trigger_terminal_name

Returns the fully qualified name for the Reference Trigger terminal. You can use this terminal as the source for another trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Terminal Name
- C Attribute: NISCOPE_ATTR_REF_TRIGGER_TERMINAL_NAME

ref_trig_tdc_enable

niscope.Session.ref_trig_tdc_enable

This property controls whether the TDC is used to compute an accurate trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Horizontal:Advanced:Enable TDC
- C Attribute: NISCOPE_ATTR_REF_TRIG_TDC_ENABLE

resolution

niscope.Session.resolution

Indicates the bit width of valid data (as opposed to padding bits) in the acquired waveform. Compare to <code>niscope.Session.binary_sample_width</code>.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Acquisition:Resolution

• C Attribute: NISCOPE_ATTR_RESOLUTION

ris_in_auto_setup_enable

niscope.Session.ris_in_auto_setup_enable

Indicates whether the digitizer should use RIS sample rates when searching for a frequency in autosetup. Valid Values: True (1) - Use RIS sample rates in autosetup False (0) - Do not use RIS sample rates in autosetup

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Acquisition: Advanced: Enable RIS in Auto Setup
- C Attribute: NISCOPE_ATTR_RIS_IN_AUTO_SETUP_ENABLE

ris_method

niscope.Session.ris_method

Specifies the algorithm for random-interleaved sampling, which is used if the sample rate exceeds the value of niscope. Session.max_real_time_sampling_rate.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.RISMethod
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Horizontal:RIS Method

• C Attribute: NISCOPE_ATTR_RIS_METHOD

ris_num_averages

niscope.Session.ris_num_averages

The number of averages for each bin in an RIS acquisition. The number of averages times the over-sampling factor is the minimum number of real-time acquisitions necessary to reconstruct the RIS waveform. Averaging is useful in RIS because the trigger times are not evenly spaced, so adjacent points in the reconstructed waveform not be accurately spaced. By averaging, the errors in both time and voltage are smoothed.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Horizontal:RIS Num Avg

• C Attribute: NISCOPE_ATTR_RIS_NUM_AVERAGES

runt_high_threshold

niscope.Session.runt_high_threshold

Specifies the higher of two thresholds, in volts, that bound the vertical range to examine for runt pulses.

The runt threshold that causes the oscilloscope to trigger depends on the runt polarity you select. Refer to the *niscope*. *Session.runt_polarity* property for more information.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_RUNT_HIGH_THRESHOLD

runt low threshold

niscope.Session.runt_low_threshold

Specifies the lower of two thresholds, in volts, that bound the vertical range to examine for runt pulses.

The runt threshold that causes the oscilloscope to trigger depends on the runt polarity you select. Refer to the <code>niscope.Session.runt_polarity</code> property for more information.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_RUNT_LOW_THRESHOLD

runt polarity

niscope.Session.runt_polarity

Specifies the polarity of pulses that trigger the oscilloscope for runt triggering.

When set to *POSITIVE*, the oscilloscope triggers when the following conditions are met:

- The leading edge of a pulse crosses the *niscope.Session.runt_low_threshold* in a positive direction;
- The trailing edge of the pulse crosses the *niscope*. Session.runt_low_threshold in a negative direction; and
- No portion of the pulse crosses the *niscope*. Session.runt_high_threshold.

When set to NEGATIVE, the oscilloscope triggers when the following conditions are met:

- The leading edge of a pulse crosses the niscope. Session.runt_high_threshold in a negative direction;
- The trailing edge of the pulse crosses the *niscope*. *Session.runt_high_threshold* in a positive direction; and
- No portion of the pulse crosses the niscope. Session.runt_low_threshold.

When set to EITHER, the oscilloscope triggers in either case.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.RuntPolarity
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_RUNT_POLARITY

runt_time_condition

${\tt niscope.Session.} {\bf runt_time_condition}$

Specifies whether runt triggers are time qualified, and if so, how the oscilloscope triggers in relation to the duration range bounded by the <code>niscope.Session.runt_time_low_limit</code> and <code>niscope.Session.runt_time_high_limit</code> properties.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.RuntTimeCondition
Permissions	read-write
Repeated Capabilities	None

• C Attribute: NISCOPE_ATTR_RUNT_TIME_CONDITION

runt time high limit

niscope.Session.runt_time_high_limit

Specifies, in seconds, the high runt threshold time.

This property sets the upper bound on the duration of runt pulses that may trigger the oscilloscope. The <code>niscope.Session.runt_time_condition</code> property determines how the oscilloscope triggers in relation to the runt time limits.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_RUNT_TIME_HIGH_LIMIT

runt_time_low_limit

niscope.Session.runt_time_low_limit

Specifies, in seconds, the low runt threshold time.

This property sets the lower bound on the duration of runt pulses that may trigger the oscilloscope. The <code>niscope.Session.runt_time_condition</code> property determines how the oscilloscope triggers in relation to the runt time limits.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_RUNT_TIME_LOW_LIMIT

sample mode

niscope.Session.sample_mode

Indicates the sample mode the digitizer is currently using.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Acquisition:Sample Mode

• C Attribute: NISCOPE ATTR SAMPLE MODE

samp clk timebase div

niscope.Session.samp_clk_timebase_div

If *niscope*. *Session*. *samp_clk_timebase_src* is an external source, specifies the ratio between the sample clock timebase rate and the actual sample rate, which can be slower.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Clocking:Sample Clock Timebase Divisor

• C Attribute: NISCOPE_ATTR_SAMP_CLK_TIMEBASE_DIV

sample clock timebase multiplier

niscope.Session.sample_clock_timebase_multiplier

If niscope.Session.samp_clk_timebase_src is an external source, this property specifies the ratio between the niscope.Session.samp_clk_timebase_rate and the actual sample rate, which can be higher. This property can be used in conjunction with niscope.Session. samp_clk_timebase_div. Some devices use multiple ADCs to sample the same channel at an effective sample rate that is greater than the specified clock rate. When providing an external sample clock use this property to indicate when you want a higher sample rate. Valid values for this property vary by device and current configuration.

Related topics: Sample Clock

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_SAMP_CLK_TIMEBASE_MULT

samp clk timebase rate

niscope.Session.samp_clk_timebase_rate

If niscope. Session. samp_clk_timebase_src is an external source, specifies the frequency in hertz of the external clock used as the timebase source.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Clocking:Sample Clock Timebase Rate
- C Attribute: NISCOPE_ATTR_SAMP_CLK_TIMEBASE_RATE

samp clk timebase src

niscope.Session.samp_clk_timebase_src

Specifies the source of the sample clock timebase, which is the timebase used to control waveform sampling. The actual sample rate may be the timebase itself or a divided version of the timebase, depending on the <code>niscope.Session.min_sample_rate</code> (for internal sources) or the <code>niscope.Session.samp_clk_timebase_div</code> (for external sources).

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Clocking:Sample Clock Timebase Source
- C Attribute: NISCOPE_ATTR_SAMP_CLK_TIMEBASE_SRC

serial number

niscope.Session.serial_number

Returns the serial number of the device.

Tip: This property can be set/get on specific instruments within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container instruments to specify a subset.

Example: my_session.instruments[...].serial_number

To set/get on all instruments, you can call the property directly on the niscope. Session.

Example: my_session.serial_number

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	instruments

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Device:Serial Number

• C Attribute: NISCOPE_ATTR_SERIAL_NUMBER

accessory_gain

niscope.Session.accessory_gain

Returns the calibration gain for the current device configuration.

Related topics: NI 5122/5124/5142 Calibration

Note: This property is supported only by the NI PXI-5900 differential amplifier.

Tip: This property can be set/get on specific channels within your *niscope.Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].accessory_gain

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.accessory_gain

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_SIGNAL_COND_GAIN

accessory_offset

niscope.Session.accessory_offset

Returns the calibration offset for the current device configuration.

Related topics: NI 5122/5124/5142 Calibration

Note: This property is supported only by the NI PXI-5900 differential amplifier.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].accessory_offset

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.accessory_offset

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read only
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_SIGNAL_COND_OFFSET

simulate

niscope.Session.simulate

Specifies whether or not to simulate instrument driver I/O operations. If simulation is enabled, instrument driver methods perform range checking and call Ivi_GetAttribute and Ivi_SetAttribute methods, but they do not perform instrument I/O. For output parameters that represent instrument data, the instrument driver methods return calculated values. The default value is False. Use the niscope. Session.__init__() method to override this value.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes: User Options: Simulate
- C Attribute: NISCOPE_ATTR_SIMULATE

specific_driver_description

$\verb|niscope.Session.specific_driver_description|\\$

A string that contains a brief description of the specific driver

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Inherent IVI Attributes:Driver Identification:Description
- C Attribute: NISCOPE_ATTR_SPECIFIC_DRIVER_DESCRIPTION

specific driver revision

niscope.Session.specific_driver_revision

A string that contains additional version information about this instrument driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes:Driver Identification:Revision
- C Attribute: NISCOPE_ATTR_SPECIFIC_DRIVER_REVISION

specific driver vendor

niscope.Session.specific_driver_vendor

A string that contains the name of the vendor that supplies this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Inherent IVI Attributes:Driver Identification:Driver Vendor
- C Attribute: NISCOPE_ATTR_SPECIFIC_DRIVER_VENDOR

start to ref trigger holdoff

niscope.Session.start_to_ref_trigger_holdoff

Pass the length of time you want the digitizer to wait after it starts acquiring data until the digitizer enables the trigger system to detect a reference (stop) trigger. Units: Seconds Valid Values: 0.0 - 171.8

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Start To Ref Trigger Holdoff
- C Attribute: NISCOPE_ATTR_START_TO_REF_TRIGGER_HOLDOFF

start_trigger_terminal_name

niscope.Session.start_trigger_terminal_name

Returns the fully qualified name for the Start Trigger terminal. You can use this terminal as the source for another trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Synchronization:Start Trigger (Acq. Arm):Terminal Name
- C Attribute: NISCOPE_ATTR_START_TRIGGER_TERMINAL_NAME

supported_instrument_models

niscope.Session.supported_instrument_models

A string that contains a comma-separated list of the instrument model numbers supported by this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read only
Repeated Capabilities	None

- LabVIEW Property: Inherent IVI Attributes:Driver Capabilities:Supported Instrument Models
- C Attribute: NISCOPE_ATTR_SUPPORTED_INSTRUMENT_MODELS

trigger auto triggered

niscope.Session.trigger_auto_triggered

Specifies if the last acquisition was auto triggered. You can use the Auto Triggered property to find out if the last acquisition was triggered.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read only
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Auto Triggered
- C Attribute: NISCOPE_ATTR_TRIGGER_AUTO_TRIGGERED

trigger_coupling

niscope.Session.trigger_coupling

Specifies how the digitizer couples the trigger source. This property affects instrument operation only when <code>niscope.Session.trigger_type</code> is set to <code>EDGE</code>, <code>HYSTERESIS</code>, or <code>WINDOW</code>.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.TriggerCoupling
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Triggering:Trigger Coupling
- C Attribute: NISCOPE_ATTR_TRIGGER_COUPLING

trigger_delay_time

niscope.Session.trigger_delay_time

Specifies the trigger delay time in seconds. The trigger delay time is the length of time the digitizer waits after it receives the trigger. The event that occurs when the trigger delay elapses is the Reference Event. Valid Values: 0.0 - 171.8

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Trigger Delay
- C Attribute: NISCOPE_ATTR_TRIGGER_DELAY_TIME

trigger holdoff

niscope.Session.trigger_holdoff

Specifies the length of time (in seconds) the digitizer waits after detecting a trigger before enabling the trigger subsystem to detect another trigger. This property affects instrument operation only when the digitizer requires multiple acquisitions to build a complete waveform. The digitizer requires multiple waveform acquisitions when it uses equivalent-time sampling or when the digitizer is configured for a multi-record acquisition through a call to niscope. Session. configure_horizontal_timing(). Valid Values: 0.0 - 171.8

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	hightime.timedelta, datetime.timedelta, or float in seconds
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: **Triggering:Trigger Holdoff**
- C Attribute: NISCOPE_ATTR_TRIGGER_HOLDOFF

trigger_hysteresis

niscope.Session.trigger_hysteresis

Specifies the size of the hysteresis window on either side of the trigger level. The digitizer triggers when the trigger signal passes through the threshold you specify with the Trigger Level parameter, has the slope you specify with the Trigger Slope parameter, and passes through the hysteresis window that you specify with this parameter.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Hysteresis

• C Attribute: NISCOPE_ATTR_TRIGGER_HYSTERESIS

trigger_impedance

niscope.Session.trigger_impedance

Specifies the input impedance for the external analog trigger channel in Ohms. Valid Values: 50 - 50 ohms 1000000 - 1 mega ohm

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Impedance

• C Attribute: NISCOPE_ATTR_TRIGGER_IMPEDANCE

trigger level

niscope.Session.trigger_level

Specifies the voltage threshold for the trigger subsystem. The units are volts. This property affects instrument behavior only when the <code>niscope.Session.trigger_type</code> is set to <code>EDGE</code>, <code>HYSTERESIS</code>, or <code>WINDOW</code>. Valid Values: The values of the range and offset parameters in <code>niscope.Session.configure_vertical()</code> determine the valid range for the trigger level on the channel you use as the Trigger Source. The value you pass for this parameter must meet the following conditions:

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Level

• C Attribute: NISCOPE_ATTR_TRIGGER_LEVEL

trigger_modifier

niscope.Session.trigger_modifier

Configures the device to automatically complete an acquisition if a trigger has not been received. Valid Values: None (1) - Normal triggering Auto Trigger (2) - Auto trigger acquisition if no trigger arrives

The following table lists the characteristics of this property.

Value
enums.TriggerModifier
read-write
None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Modifier

• C Attribute: NISCOPE_ATTR_TRIGGER_MODIFIER

trigger_slope

niscope.Session.trigger_slope

Specifies if a rising or a falling edge triggers the digitizer. This property affects instrument operation only when *niscope*. Session. trigger_type is set to EDGE, HYSTERESIS, or WINDOW.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.TriggerSlope
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Slope

• C Attribute: NISCOPE_ATTR_TRIGGER_SLOPE

trigger_source

niscope.Session.trigger_source

Specifies the source the digitizer monitors for the trigger event.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	str
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Source

• C Attribute: NISCOPE_ATTR_TRIGGER_SOURCE

trigger_type

niscope.Session.trigger_type

Specifies the type of trigger to use.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.TriggerType
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Type

• C Attribute: NISCOPE_ATTR_TRIGGER_TYPE

trigger_window_high_level

niscope.Session.trigger_window_high_level

Pass the upper voltage threshold you want the digitizer to use for window triggering. The digitizer triggers when the trigger signal enters or leaves the window you specify with <code>niscope.Session.trigger_window_low_level</code> and <code>niscope.Session.trigger_window_high_level</code> Valid Values: The values of the Vertical Range and Vertical Offset parameters in <code>niscope.Session.configure_vertical()</code> determine the valid range for the High Window Level on the channel you use as the Trigger Source parameter in <code>niscope.Session.ConfigureTriggerSource()</code>. The value you pass for this parameter must meet the following conditions. High Trigger Level <= Vertical Range/2 + Vertical Offset High Trigger Level >= (-Vertical Range/2) + Vertical Offset High Trigger Level > Low Trigger Level

Note: One or more of the referenced methods are not in the Python API for this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Triggering:Trigger Window:High Level
- C Attribute: NISCOPE_ATTR_TRIGGER_WINDOW_HIGH_LEVEL

trigger_window_low_level

niscope.Session.trigger_window_low_level

Pass the lower voltage threshold you want the digitizer to use for window triggering. The digitizer triggers when the trigger signal enters or leaves the window you specify with <code>niscope.Session.trigger_window_low_level</code> and <code>niscope.Session.trigger_window_high_level</code>. Units: Volts Valid Values: The values of the Vertical Range and Vertical Offset parameters in <code>niscope.Session.configure_vertical()</code> determine the valid range for the Low Window Level on the channel you use as the Trigger Source parameter in <code>niscope.Session.ConfigureTriggerSource()</code>. The value you pass for this parameter must meet the following conditions. Low Trigger Level <= Vertical Range/2 + Vertical Offset Low Trigger Level >= (-Vertical Range/2) + Vertical Offset Low Trigger Level < High Trigger Level

Note: One or more of the referenced methods are not in the Python API for this driver.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Trigger Window:Low Level
- C Attribute: NISCOPE_ATTR_TRIGGER_WINDOW_LOW_LEVEL

trigger_window_mode

niscope.Session.trigger_window_mode

Specifies whether you want a trigger to occur when the signal enters or leaves the window specified by niscope. Session.trigger_window_low_level, or niscope. Session.trigger_window_high_level.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.TriggerWindowMode
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Triggering:Trigger Window:Window Mode
- C Attribute: NISCOPE ATTR TRIGGER WINDOW MODE

tv_trigger_event

niscope.Session.tv_trigger_event

Specifies the condition in the video signal that causes the digitizer to trigger.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.VideoTriggerEvent
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Triggering:Trigger Video:Event

• C Attribute: NISCOPE_ATTR_TV_TRIGGER_EVENT

tv_trigger_line_number

niscope.Session.tv_trigger_line_number

Specifies the line on which to trigger, if *niscope*. *Session*. *tv_trigger_event* is set to line number. The valid ranges of the property depend on the signal format selected. M-NTSC has a valid range of 1 to 525. B/G-PAL, SECAM, 576i, and 576p have a valid range of 1 to 625. 720p has a valid range of 1 to 750. 1080i and 1080p have a valid range of 1125.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	int
Permissions	read-write
Repeated Capabilities	None

- LabVIEW Property: Triggering:Trigger Video:Line Number
- C Attribute: NISCOPE_ATTR_TV_TRIGGER_LINE_NUMBER

tv_trigger_polarity

niscope.Session.tv_trigger_polarity

Specifies whether the video signal sync is positive or negative.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.VideoPolarity
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Trigger Video:Polarity
- C Attribute: NISCOPE_ATTR_TV_TRIGGER_POLARITY

tv_trigger_signal_format

niscope.Session.tv_trigger_signal_format

Specifies the type of video signal, such as NTSC, PAL, or SECAM.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.VideoSignalFormat
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Triggering:Trigger Video:Signal Format
- C Attribute: NISCOPE_ATTR_TV_TRIGGER_SIGNAL_FORMAT

use spec initial x

niscope.Session.use_spec_initial_x

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	bool
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE ATTR USE SPEC INITIAL X

vertical coupling

niscope.Session.vertical_coupling

Specifies how the digitizer couples the input signal for the channel. When input coupling changes, the input stage takes a finite amount of time to settle.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].vertical_coupling

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.vertical_coupling

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.VerticalCoupling
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

- LabVIEW Property: Vertical: Vertical Coupling
- C Attribute: NISCOPE_ATTR_VERTICAL_COUPLING

vertical_offset

niscope.Session.vertical_offset

Specifies the location of the center of the range. The value is with respect to ground and is in volts. For example, to acquire a sine wave that spans between 0.0 and 10.0 V, set this property to 5.0 V.

Note: This property is not supported by all digitizers.Refer to the NI High-Speed Digitizers Help for a list of vertical offsets supported for each device.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].vertical_offset

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.vertical_offset

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Vertical: Vertical Offset

• C Attribute: NISCOPE_ATTR_VERTICAL_OFFSET

vertical_range

niscope.Session.vertical_range

Specifies the absolute value of the input range for a channel in volts. For example, to acquire a sine wave that spans between -5 and +5 V, set this property to 10.0 V. Refer to the NI High-Speed Digitizers Help for a list of supported vertical ranges for each device. If the specified range is not supported by a device, the value is coerced up to the next valid range.

Tip: This property can be set/get on specific channels within your *niscope*. *Session* instance. Use Python index notation on the repeated capabilities container channels to specify a subset.

Example: my_session.channels[...].vertical_range

To set/get on all channels, you can call the property directly on the niscope. Session.

Example: my_session.vertical_range

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	channels

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• LabVIEW Property: Vertical: Vertical Range

• C Attribute: NISCOPE_ATTR_VERTICAL_RANGE

width_condition

niscope.Session.width_condition

Specifies whether the oscilloscope triggers on pulses within or outside the duration range bounded by the *niscope.Session.width_low_threshold* and *niscope.Session.width_high_threshold* properties.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.WidthCondition
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_WIDTH_CONDITION

width_high_threshold

niscope.Session.width_high_threshold

Specifies the high width threshold, in seconds.

This properties sets the upper bound on the duration range that triggers the oscilloscope. The <code>niscope.Session.width_condition</code> property determines how the oscilloscope triggers in relation to the width thresholds.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_WIDTH_HIGH_THRESHOLD

width_low_threshold

niscope.Session.width_low_threshold

Specifies the low width threshold, in seconds.

This property sets the lower bound on the duration range that triggers the oscilloscope. The *niscope*. *Session.width_condition* property determines how the oscilloscope triggers in relation to the width thresholds.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	float
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_WIDTH_LOW_THRESHOLD

width_polarity

niscope.Session.width_polarity

Specifies the polarity of pulses that trigger the oscilloscope for width triggering.

The following table lists the characteristics of this property.

Characteristic	Value
Datatype	enums.WidthPolarity
Permissions	read-write
Repeated Capabilities	None

Tip: This property corresponds to the following LabVIEW Property or C Attribute:

• C Attribute: NISCOPE_ATTR_WIDTH_POLARITY

NI-TClk Support

niscope.Session.tclk

This is used to get and set NI-TClk attributes on the session.

See also:

See nitclk.SessionReference for a complete list of attributes.

Session

- Session
- Methods
 - abort
 - acquisition_status
 - add_waveform_processing
 - auto_setup
 - clear_waveform_measurement_stats
 - clear_waveform_processing
 - close
 - commit
 - configure_chan_characteristics
 - configure_equalization_filter_coefficients
 - configure_horizontal_timing
 - configure_trigger_digital
 - configure_trigger_edge
 - configure_trigger_hysteresis
 - configure_trigger_immediate
 - configure_trigger_software
 - configure_trigger_video
 - configure_trigger_window
 - configure_vertical
 - disable
 - export_attribute_configuration_buffer
 - export_attribute_configuration_file
 - fetch
 - fetch_array_measurement
 - fetch_into
 - fetch_measurement_stats
 - get_channel_names
 - get_equalization_filter_coefficients
 - get_ext_cal_last_date_and_time
 - get_ext_cal_last_temp
 - get_self_cal_last_date_and_time
 - get_self_cal_last_temp
 - import_attribute_configuration_buffer

- import_attribute_configuration_file
- initiate
- lock
- probe_compensation_signal_start
- probe_compensation_signal_stop
- read
- reset
- reset_device
- reset_with_defaults
- self_cal
- self_test
- send_software_trigger_edge
- unlock

• Properties

- absolute_sample_clock_offset
- acquisition_start_time
- acquisition_type
- acq_arm_source
- advance_trigger_terminal_name
- adv_trig_src
- allow_more_records_than_memory
- arm_ref_trig_src
- backlog
- bandpass_filter_enabled
- binary_sample_width
- cable_sense_mode
- cable_sense_signal_enable
- cable_sense_voltage
- channel_count
- channel_enabled
- channel_terminal_configuration
- data_transfer_block_size
- data_transfer_maximum_bandwidth
- data_transfer_preferred_packet_size
- device_temperature

- enabled_channels
- enable_dc_restore
- enable_time_interleaved_sampling
- end_of_acquisition_event_output_terminal
- end_of_acquisition_event_terminal_name
- end_of_record_event_output_terminal
- end_of_record_event_terminal_name
- end_of_record_to_advance_trigger_holdoff
- equalization_filter_enabled
- equalization_num_coefficients
- exported_advance_trigger_output_terminal
- exported_ref_trigger_output_terminal
- exported_start_trigger_output_terminal
- flex_fir_antialias_filter_type
- fpga_bitfile_path
- glitch_condition
- glitch_polarity
- glitch_width
- high_pass_filter_frequency
- horz_enforce_realtime
- horz_min_num_pts
- horz_num_records
- horz_record_length
- horz_record_ref_position
- horz_sample_rate
- horz_time_per_record
- input_clock_source
- input_impedance
- instrument_firmware_revision
- instrument_manufacturer
- instrument_model
- interleaving_offset_correction_enabled
- io_resource_descriptor
- is_probe_comp_on
- logical_name

- master_enable
- max_input_frequency
- max_real_time_sampling_rate
- max_ris_rate
- meas_array_gain
- meas_array_offset
- meas_chan_high_ref_level
- meas_chan_low_ref_level
- meas_chan_mid_ref_level
- meas_filter_center_freq
- meas_filter_cutoff_freq
- meas_filter_order
- meas_filter_ripple
- meas_filter_taps
- meas_filter_transient_waveform_percent
- meas_filter_type
- meas_filter_width
- meas_fir_filter_window
- meas_high_ref
- meas_hysteresis_percent
- meas_interpolation_sampling_factor
- meas_last_acq_histogram_size
- meas_low_ref
- meas_mid_ref
- meas_other_channel
- meas_percentage_method
- meas_polynomial_interpolation_order
- meas_ref_level_units
- meas_time_histogram_high_time
- meas_time_histogram_high_volts
- meas_time_histogram_low_time
- meas_time_histogram_low_volts
- meas_time_histogram_size
- meas_voltage_histogram_high_volts
- meas_voltage_histogram_low_volts

- meas_voltage_histogram_size
- min_sample_rate
- onboard_memory_size
- output_clock_source
- pll_lock_status
- points_done
- poll_interval
- probe_attenuation
- ready_for_advance_event_output_terminal
- ready_for_advance_event_terminal_name
- ready_for_ref_event_output_terminal
- ready_for_ref_event_terminal_name
- ready_for_start_event_output_terminal
- ready_for_start_event_terminal_name
- records_done
- record_arm_source
- ref_clk_rate
- ref_trigger_detector_location
- ref_trigger_minimum_quiet_time
- ref_trigger_terminal_name
- ref_trig_tdc_enable
- resolution
- ris_in_auto_setup_enable
- ris_method
- ris_num_averages
- runt_high_threshold
- runt_low_threshold
- runt_polarity
- runt_time_condition
- runt_time_high_limit
- runt_time_low_limit
- sample_mode
- samp_clk_timebase_div
- sample_clock_timebase_multiplier
- samp_clk_timebase_rate

- samp_clk_timebase_src
- serial_number
- accessory_gain
- accessory_offset
- simulate
- specific_driver_description
- specific_driver_revision
- specific_driver_vendor
- start_to_ref_trigger_holdoff
- start_trigger_terminal_name
- supported_instrument_models
- trigger_auto_triggered
- trigger_coupling
- trigger_delay_time
- trigger_holdoff
- trigger_hysteresis
- trigger_impedance
- trigger_level
- trigger_modifier
- trigger_slope
- trigger_source
- trigger_type
- trigger_window_high_level
- trigger_window_low_level
- trigger_window_mode
- tv_trigger_event
- tv_trigger_line_number
- $-\ tv_trigger_polarity$
- tv_trigger_signal_format
- use_spec_initial_x
- vertical_coupling
- vertical_offset
- vertical_range
- width_condition
- width_high_threshold

- width_low_threshold
- width_polarity
- NI-TClk Support

Repeated Capabilities

Repeated capabilities attributes are used to set the *channel_string* parameter to the underlying driver function call. This can be the actual function based on the Session method being called, or it can be the appropriate Get/Set Attribute function, such as niScope_SetAttributeViInt32().

Repeated capabilities attributes use the indexing operator [] to indicate the repeated capabilities. The parameter can be a string, list, tuple, or slice (range). Each element of those can be a string or an integer. If it is a string, you can indicate a range using the same format as the driver: '0-2' or '0:2'

Some repeated capabilities use a prefix before the number and this is optional

channels

niscope.Session.channels

```
session.channels['0-2'].channel_enabled = True
```

passes a string of '0, 1, 2' to the set attribute function.

instruments

niscope. Session. instruments

```
session.instruments['0-2'].channel_enabled = True
```

passes a string of '0, 1, 2' to the set attribute function.

Enums

Enums used in NI-SCOPE

AcquisitionStatus

class niscope.AcquisitionStatus

COMPLETE

IN_PROGRESS

STATUS_UNKNOWN

AcquisitionType

class niscope.AcquisitionType

NORMAL

Sets the digitizer to normal resolution mode. The digitizer can use real-time sampling or equivalent-time sampling.

FLEXRES

Sets the digitizer to flexible resolution mode if supported. The digitizer uses different hardware configurations to change the resolution depending on the sampling rate used.

DDC

Sets the digitizer to DDC mode on the NI 5620/5621.

ArrayMeasurement

class niscope.ArrayMeasurement

NO_MEASUREMENT

None

LAST_ACQ_HISTOGRAM

Last Acquisition Histogram

FFT_PHASE_SPECTRUM

FFT Phase Spectrum

FFT_AMP_SPECTRUM_VOLTS_RMS

FFT Amp. Spectrum (Volts RMS)

MULTI_ACQ_VOLTAGE_HISTOGRAM

Multi Acquisition Voltage Histogram

MULTI_ACQ_TIME_HISTOGRAM

Multi Acquisition Time Histogram

ARRAY_INTEGRAL

Array Integral

DERIVATIVE

Derivative

INVERSE

Inverse

HANNING_WINDOW

Hanning Window

FLAT_TOP_WINDOW

Flat Top Window

POLYNOMIAL_INTERPOLATION

Polynomial Interpolation

MULTIPLY_CHANNELS

Multiply Channels

ADD_CHANNELS

Add Channels

SUBTRACT_CHANNELS

Subtract Channels

DIVIDE_CHANNELS

Divide Channels

MULTI_ACQ_AVERAGE

Multi Acquisition Average

BUTTERWORTH_FILTER

Butterworth IIR Filter

CHEBYSHEV_FILTER

Chebyshev IIR Filter

FFT_AMP_SPECTRUM_DB

FFT Amp. Spectrum (dB)

HAMMING_WINDOW

Hamming Window

WINDOWED_FIR_FILTER

FIR Windowed Filter

BESSEL_FILTER

Bessel IIR Filter

TRIANGLE_WINDOW

Triangle Window

BLACKMAN_WINDOW

Blackman Window

ARRAY_OFFSET

Array Offset

ARRAY_GAIN

Array Gain

CableSenseMode

class niscope.CableSenseMode

DISABLED

The oscilloscope is not configured to emit a CableSense signal.

ON_DEMAND

The oscilloscope is configured to emit a single CableSense pulse.

ClearableMeasurement

class niscope.ClearableMeasurement

ALL_MEASUREMENTS

MULTI_ACQ_VOLTAGE_HISTOGRAM

MULTI_ACQ_TIME_HISTOGRAM

MULTI_ACQ_AVERAGE

FREQUENCY

AVERAGE_FREQUENCY

FFT_FREQUENCY

PERIOD

AVERAGE_PERIOD

RISE_TIME

FALL_TIME

RISE_SLEW_RATE

FALL_SLEW_RATE

OVERSHOOT

PRESHOOT

VOLTAGE_RMS

VOLTAGE_CYCLE_RMS

AC_ESTIMATE

FFT_AMPLITUDE

VOLTAGE_AVERAGE

VOLTAGE_CYCLE_AVERAGE

DC_ESTIMATE

VOLTAGE_MAX

VOLTAGE_MIN

VOLTAGE_PEAK_TO_PEAK

VOLTAGE_HIGH

VOLTAGE_LOW

AMPLITUDE

VOLTAGE_TOP VOLTAGE_BASE VOLTAGE_BASE_TO_TOP WIDTH_NEG WIDTH_POS DUTY_CYCLE_NEG DUTY_CYCLE_POS INTEGRAL **AREA** CYCLE_AREA TIME_DELAY PHASE_DELAY LOW_REF_VOLTS MID_REF_VOLTS HIGH_REF_VOLTS VOLTAGE_HISTOGRAM_MEAN VOLTAGE_HISTOGRAM_STDEV VOLTAGE_HISTOGRAM_MEDIAN VOLTAGE_HISTOGRAM_MODE VOLTAGE_HISTOGRAM_MAX VOLTAGE_HISTOGRAM_MIN VOLTAGE_HISTOGRAM_PEAK_TO_PEAK VOLTAGE_HISTOGRAM_MEAN_PLUS_STDEV VOLTAGE_HISTOGRAM_MEAN_PLUS_2_STDEV VOLTAGE_HISTOGRAM_MEAN_PLUS_3_STDEV VOLTAGE_HISTOGRAM_HITS VOLTAGE_HISTOGRAM_NEW_HITS TIME_HISTOGRAM_MEAN TIME_HISTOGRAM_STDEV TIME_HISTOGRAM_MEDIAN

TIME_HISTOGRAM_MODE

TIME_HISTOGRAM_MAX

TIME_HISTOGRAM_MIN

TIME_HISTOGRAM_PEAK_TO_PEAK

TIME_HISTOGRAM_MEAN_PLUS_STDEV

TIME_HISTOGRAM_MEAN_PLUS_2_STDEV

TIME_HISTOGRAM_MEAN_PLUS_3_STDEV

TIME_HISTOGRAM_HITS

TIME_HISTOGRAM_NEW_HITS

FIRFilterWindow

class niscope.FIRFilterWindow

NONE

No window.

HANNING

Specifies a Hanning window.

FLAT_TOP

Specifies a Flat Top window.

HAMMING

Specifies a Hamming window.

TRIANGLE

Specifies a Triangle window.

BLACKMAN

Specifies a Blackman window.

FetchRelativeTo

class niscope.FetchRelativeTo

READ_POINTER

The read pointer is set to zero when a new acquisition is initiated. After every fetch the read pointer is incremeted to be the sample after the last sample retrieved. Therefore, you can repeatedly fetch relative to the read pointer for a continuous acquisition program.

PRETRIGGER

Fetches relative to the first pretrigger point requested with *niscope*. Session. configure_horizontal_timing().

NOW

Fetch data at the last sample acquired.

START

Fetch data starting at the first point sampled by the digitizer.

TRIGGER

Fetch at the first posttrigger sample.

FilterType

class niscope.FilterType

LOWPASS

Specifies lowpass as the filter type.

HIGHPASS

Specifies highpass as the filter type.

BANDPASS

Specifies bandpass as the filter type.

BANDSTOP

Specifies bandstop as the filter type.

FlexFIRAntialiasFilterType

class niscope.FlexFIRAntialiasFilterType

FOURTYEIGHT_TAP_STANDARD

This filter is optimized for alias protection and frequency-domain flatness

FOURTYEIGHT_TAP_HANNING

This filter is optimized for the lowest possible bandwidth for a 48 tap filter and maximizes the SNR

SIXTEEN_TAP_HANNING

This filter is optimized for the lowest possible bandwidth for a 16 tap filter and maximizes the SNR

EIGHT_TAP_HANNING

This filter is optimized for the lowest possible bandwidth for a 8 tap filter and maximizes the SNR

GlitchCondition

class niscope.GlitchCondition

GREATER

Trigger on pulses with a duration greater than the specified glitch width.

LESS

Trigger on pulses with a duration shorter than the specified glitch width.

GlitchPolarity

class niscope.GlitchPolarity

POSITIVE

Trigger on pulses of positive polarity relative to the trigger threshold.

NEGATIVE

Trigger on pulses of negative polarity relative to the trigger threshold.

EITHER

Trigger on pulses of either positive or negative polarity.

Option

class niscope.Option

SELF_CALIBRATE_ALL_CHANNELS

Self Calibrating all Channels

RESTORE_EXTERNAL_CALIBRATION

Restore External Calibration.

PercentageMethod

class niscope.PercentageMethod

LOWHIGH

Specifies that the reference level percentages should be computed using the low/high method,

MINMAX

Reference level percentages are computed using the min/max method.

BASETOP

Reference level percentages are computed using the base/top method.

RISMethod

class niscope.RISMethod

EXACT_NUM_AVERAGES

Acquires exactly the specified number of records for each bin in the RIS acquisition. An error is returned from the fetch method if the RIS acquisition does not successfully acquire the specified number of waveforms within the timeout period. You may call the fetch method again to allow more time for the acquisition to finish.

MIN_NUM_AVERAGES

Each RIS sample is the average of a least a minimum number of randomly distributed points.

INCOMPLETE

Returns the RIS waveform after the specified timeout even if it is incomplete. If no waveforms have been acquired in certain bins, these bins will have a NaN (when fetching scaled data) or a zero (when fetching binary data). A warning (positive error code) is returned from the fetch method if the RIS acquisition did not finish. The acquisition aborts when data is returned.

LIMITED_BIN_WIDTH

Limits the waveforms in the various bins to be within 200 ps of the center of the bin.

RefLevelUnits

class niscope.RefLevelUnits

VOLTS

Specifies that the reference levels are given in units of volts.

PERCENTAGE

(Default) Specifies that the reference levels are given in percentage units.

RefTriggerDetectorLocation

class niscope.RefTriggerDetectorLocation

ANALOG_DETECTION_CIRCUIT

use the hardware analog circuitry to implement the reference trigger. This option will trigger before any onboard signal processing.

DDC_OUTPUT

use the onboard signal processing logic to implement the reference trigger. This option will trigger based on the onboard signal processed data.

RuntPolarity

class niscope.RuntPolarity

POSITIVE

Trigger on pulses of positive polarity relative to niscope. Session.runt_low_threshold that do not cross niscope. Session.runt_high_threshold.

NEGATIVE

Trigger on pulses of negative polarity relative to $niscope.Session.runt_high_threshold$ that do not cross $niscope.Session.runt_low_threshold$.

EITHER

Trigger on pulses of either positive or negative polarity.

RuntTimeCondition

class niscope.RuntTimeCondition

NONE

Time qualification is disabled. Trigger on runt pulses based solely on the voltage level of the pulses.

WITHIN

Trigger on pulses that, in addition to meeting runt voltage criteria, have a duration within the range bounded by <code>niscope.Session.runt_time_low_limit</code> and <code>niscope.Session.runt_time_high_limit</code>.

OUTSIDE

Trigger on pulses that, in addition to meeting runt voltage criteria, have a duration not within the range bounded by $niscope.Session.runt_time_low_limit$ and $niscope.Session.runt_time_high_limit$.

ScalarMeasurement

class niscope.ScalarMeasurement

NO_MEASUREMENT

None

RISE_TIME

FALL_TIME

FREQUENCY

PERIOD

VOLTAGE_RMS

VOLTAGE_PEAK_TO_PEAK

VOLTAGE_MAX

VOLTAGE_MIN

VOLTAGE_HIGH

VOLTAGE_LOW

VOLTAGE_AVERAGE

WIDTH_NEG

WIDTH_POS

DUTY_CYCLE_NEG

DUTY_CYCLE_POS

AMPLITUDE

VOLTAGE_CYCLE_RMS

VOLTAGE_CYCLE_AVERAGE

OVERSHOOT

	PRESHOOT
	LOW_REF_VOLTS
	MID_REF_VOLTS
	HIGH_REF_VOLTS
	AREA
	CYCLE_AREA
	INTEGRAL
	VOLTAGE_BASE
	VOLTAGE_TOP
	FFT_FREQUENCY
	FFT_AMPLITUDE
	RISE_SLEW_RATE
	FALL_SLEW_RATE
	AC_ESTIMATE
	DC_ESTIMATE
	TIME_DELAY
	AVERAGE_PERIOD
	AVERAGE_FREQUENCY
	VOLTAGE_BASE_TO_TOP
	PHASE_DELAY
Tern	minalConfiguration
clas	ss niscope.TerminalConfiguration
	SINGLE_ENDED
	Channel is single ended
	UNBALANCED_DIFFERENTIAL

Channel is unbalanced differential

Channel is differential

DIFFERENTIAL

TriggerCoupling

```
class niscope.TriggerCoupling
```

AC

AC coupling

DC

DC coupling

HF_REJECT

Highpass filter coupling

LF_REJECT

Lowpass filter coupling

AC_PLUS_HF_REJECT

Highpass and lowpass filter coupling

TriggerModifier

```
class niscope.TriggerModifier
```

NO_TRIGGER_MOD

Normal triggering.

AUTO

Software will trigger an acquisition automatically if no trigger arrives after a certain amount of time.

AUTO_LEVEL

TriggerSlope

```
class niscope.TriggerSlope
```

NEGATIVE

Falling edge

POSITIVE

Rising edge

SLOPE_EITHER

Either edge

TriggerType

class niscope.TriggerType

EDGE

Configures the digitizer for edge triggering. An edge trigger occurs when the trigger signal crosses the trigger level specified with the set trigger slope. You configure the trigger level and slope with <code>niscope</code>. <code>Session.configure_trigger_edge()</code>.

HYSTERESIS

Configures the digitizer for hysteresis triggering. A hysteresis trigger occurs when the trigger signal crosses the trigger level with the specified slope and passes through the hysteresis window you specify. You configure the trigger level, slope, and hysteresis with niscope. Session. configure_trigger_hysteresis().

DIGITAL

Configures the digitizer for digital triggering. A digital trigger occurs when the trigger signal has the specified slope. You configure the trigger slope with *niscope*. Session.configure_trigger_digital().

WINDOW

Configures the digitizer for window triggering. A window trigger occurs when the trigger signal enters or leaves the window defined by the values you specify with the Low Window Level, High Window Level, and Window Mode Parameters. You configure the low window level high window level, and window mode with niscope.Session.configure_trigger_window().

SOFTWARE

Configures the digitizer for software triggering. A software trigger occurs when niscope.Session. SendSoftwareTrigger() is called.

TV

Configures the digitizer for video/TV triggering. You configure the video trigger parameters like signal Format, Line to trigger off of, Polarity, and Enable DC Restore with *niscope.Session.configure_trigger_video()*.

GLITCH

WIDTH

RUNT

IMMEDIATE

Configures the digitizer for immediate triggering. An immediate trigger occurs as soon as the pretrigger samples are acquired.

TriggerWindowMode

class niscope.TriggerWindowMode

ENTERING

Trigger upon entering the window

LEAVING

Trigger upon leaving the window

ENTERING_OR_LEAVING

VerticalCoupling

class niscope. Vertical Coupling

AC

AC coupling

DC

DC coupling

GND

GND coupling

VideoPolarity

class niscope.VideoPolarity

POSITIVE

Specifies that the video signal has positive polarity.

NEGATIVE

Specifies that the video signal has negative polarity.

VideoSignalFormat

class niscope. Video Signal Format

NTSC

NTSC signal format supports line numbers from 1 to 525

PAL

PAL signal format supports line numbers from 1 to 625

SECAM

SECAM signal format supports line numbers from 1 to 625

M_PAL

M-PAL signal format supports line numbers from 1 to 525

VIDEO_480I_59_94_FIELDS_PER_SECOND

480 lines, interlaced, 59.94 fields per second

VIDEO_480I_60_FIELDS_PER_SECOND

480 lines, interlaced, 60 fields per second

VIDEO_480P_59_94_FRAMES_PER_SECOND

480 lines, progressive, 59.94 frames per second

VIDEO_480P_60_FRAMES_PER_SECOND

480 lines, progressive,60 frames per second

VIDEO_576I_50_FIELDS_PER_SECOND

576 lines, interlaced, 50 fields per second

VIDEO_576P_50_FRAMES_PER_SECOND

576 lines, progressive, 50 frames per second

VIDEO_720P_50_FRAMES_PER_SECOND

720 lines, progressive, 50 frames per second

VIDEO_720P_59_94_FRAMES_PER_SECOND

720 lines, progressive, 59.94 frames per second

VIDEO_720P_60_FRAMES_PER_SECOND

720 lines, progressive, 60 frames per second

VIDEO_1080I_50_FIELDS_PER_SECOND

1,080 lines, interlaced, 50 fields per second

VIDEO_1080I_59_94_FIELDS_PER_SECOND

1,080 lines, interlaced, 59.94 fields per second

VIDEO_1080I_60_FIELDS_PER_SECOND

1,080 lines, interlaced, 60 fields per second

VIDEO_1080P_24_FRAMES_PER_SECOND

1,080 lines, progressive, 24 frames per second

VideoTriggerEvent

class niscope.VideoTriggerEvent

FIELD1

Trigger on field 1 of the signal

FIELD2

Trigger on field 2 of the signal

ANY_FIELD

Trigger on the first field acquired

ANY LINE

Trigger on the first line acquired

LINE NUMBER

Trigger on a specific line of a video signal. Valid values vary depending on the signal format configured.

WhichTrigger

class niscope.WhichTrigger

START

ARM_REFERENCE

REFERENCE

ADVANCE

WidthCondition

class niscope. Width Condition

WITHIN

Trigger on pulses with a duration within the range bounded by niscope. Session. width_low_threshold and niscope. Session.width_high_threshold.

OUTSIDE

Trigger on pulses with a duration not within the range bounded by niscope. Session. width_low_threshold and niscope. Session.width_high_threshold.

WidthPolarity

class niscope.WidthPolarity

POSITIVE

Trigger on pulses of positive polarity relative to the trigger threshold.

NEGATIVE

Trigger on pulses of negative polarity relative to the trigger threshold.

EITHER

Trigger on pulses of either positive or negative polarity.

Exceptions and Warnings

Error

exception niscope.errors.Error

Base exception type that all NI-SCOPE exceptions derive from

DriverError

exception niscope.errors.DriverError

An error originating from the NI-SCOPE driver

UnsupportedConfigurationError

exception niscope.errors.UnsupportedConfigurationError

An error due to using this module in an usupported platform.

DriverNotInstalledError

exception niscope.errors.DriverNotInstalledError

An error due to using this module without the driver runtime installed.

DriverTooOldError

exception niscope.errors.DriverTooOldError

An error due to using this module with an older version of the NI-SCOPE driver runtime.

DriverTooNewError

exception niscope.errors.DriverTooNewError

An error due to the NI-SCOPE driver runtime being too new for this module.

InvalidRepeatedCapabilityError

exception niscope.errors.InvalidRepeatedCapabilityError

An error due to an invalid character in a repeated capability

SelfTestError

exception niscope.errors.SelfTestError

An error due to a failed self-test

RpcError

exception niscope.errors.RpcError

An error specific to sessions to the NI gRPC Device Server

DriverWarning

exception niscope.errors.DriverWarning

A warning originating from the NI-SCOPE driver

Examples

You can download all niscope examples here

niscope_fetch.py

Listing 1: (niscope_fetch.py)

```
#!/usr/bin/python
2
   import argparse
   import niscope
   import pprint
   import sys
   pp = pprint.PrettyPrinter(indent=4, width=80)
10
   def example(resource_name, channels, options, length, voltage):
11
       with niscope.Session(resource_name=resource_name, options=options) as session:
12
           session.configure_vertical(range=voltage, coupling=niscope.VerticalCoupling.AC)
13
           session.configure_horizontal_timing(min_sample_rate=50000000, min_num_pts=length,
   → ref_position=50.0, num_records=1, enforce_realtime=True)
           with session.initiate():
                waveforms = session.channels[channels].fetch(num_samples=length)
16
           for i in range(len(waveforms)):
               print(f'Waveform {i} information:')
18
               print(str(waveforms[i]) + '\n\n')
19
20
21
   def _main(argsv):
22
       parser = argparse.ArgumentParser(description='Acquires one record from the given_
23
   → channels.', formatter_class=argparse.ArgumentDefaultsHelpFormatter)
       parser.add_argument('-n', '--resource-name', default='PXI1Slot2', help='Resource_
24
   →name of an NI digitizer.')
       parser.add_argument('-c', '--channels', default='0', help='Channel(s) to use')
25
       parser.add_argument('-l', '--length', default=1000, type=int, help='Measure record_
       parser.add_argument('-v', '--voltage', default=1.0, type=float, help='Voltage range_
   (V) ')
       parser.add_argument('-op', '--option-string', default='', type=str, help='Option_

    string')
       args = parser.parse_args(argsv)
       example(args.resource_name, args.channels, args.option_string, args.length, args.
30
   →voltage)
31
32
   def main():
33
       _main(sys.argv[1:])
35
   def test_example():
37
       options = {'simulate': True, 'driver_setup': {'Model': '5164', 'BoardType': 'PXIe', }
38
       example('PXI1Slot2', '0', options, 1000, 1.0)
39
41
                                                                                 (continues on next page)
```

```
def test_main():
    cmd_line = ['--option-string', 'Simulate=1, DriverSetup=Model:5164; BoardType:PXIe',
    cmd_line = ['--option-string', 'Simulate=1, DriverSetup=Model:
```

niscope_fetch_forever.py

Listing 2: (niscope_fetch_forever.py)

```
#!/usr/bin/python
2
   import argparse
   import hightime
   import niscope
   import numpy as np
   import pprint
   import sys
   pp = pprint.PrettyPrinter(indent=4, width=80)
11
12
13
   # We use fetch_into which allows us to allocate a single buffer per channel and "fetch_
   →into" it a section at a time without having to
   # reconstruct the waveform once we are done
   def example(resource_name, options, total_acquisition_time_in_seconds, voltage, sample_
16
   →rate_in_hz, samples_per_fetch):
       total_samples = int(total_acquisition_time_in_seconds * sample_rate_in_hz)
17
       # 1. Opening session
18
       with niscope.Session(resource_name=resource_name, options=options) as session:
19
           # We will acquire on all channels of the device
20
           channel_list = [c for c in range(session.channel_count)] # Need an actual list_
   →and not a range
22
           # 2. Creating numpy arrays
23
           waveforms = [np.ndarray(total_samples, dtype=np.float64) for c in channel_list]
25
           # 3. Configuring
           session.configure_horizontal_timing(min_sample_rate=sample_rate_in_hz, min_num_
27
   →pts=1, ref_position=0.0, num_records=1, enforce_realtime=True)
           session.channels[channel_list].configure_vertical(voltage, coupling=niscope.
28
   → VerticalCoupling.DC, enabled=True)
           # Configure software trigger, but never send the trigger.
29
           # This starts an infinite acquisition, until you call session.abort() or session.
   \hookrightarrow close()
```

(continues on next page)

```
session.configure_trigger_software()
31
           current_pos = 0
32
           # 4. initiating
33
           with session.initiate():
                while current_pos < total_samples:</pre>
35
                    # We fetch each channel at a time so we don't have to de-interleave.
    →afterwards
                    # We do not keep the wfm_info returned from fetch_into
37
                    for channel, waveform in zip(channel_list, waveforms):
38
                        # 5. fetching - we return the slice of the waveform array that we_{	extsf{	iny 1}}
   →want to "fetch into"
                        session.channels[channel].fetch_into(waveform[current_pos:current_
40
   -pos + samples_per_fetch], relative_to=niscope.FetchRelativeTo.READ_POINTER,
                                                               offset=0, record_number=0, num_
41
   →records=1, timeout=hightime.timedelta(seconds=5.0))
                    current_pos += samples_per_fetch
42.
44
   def _main(argsv):
45
       parser = argparse.ArgumentParser(description='Fetch more samples than will fit in...)
46

¬memory.', formatter_class=argparse.ArgumentDefaultsHelpFormatter)

       parser.add_argument('-n', '--resource-name', default='PXI1Slot2', help='Resource_
47
    →name of an NI digitizer.')
       parser.add_argument('-t', '--time', default=10, type=int, help='Time to sample (s)')
48
       parser.add_argument('-v', '--voltage', default=1.0, type=float, help='Voltage range_
   (V) ')
       parser.add_argument('-op', '--option-string', default='', type=str, help='Option_
   parser.add_argument('-r', '--sample-rate', default=1000.0, type=float, help='Sample_
51
   →Rate (Hz)')
       parser.add_argument('-s', '--samples-per-fetch', default=100, type=int, help=
52
   →'Samples per fetch')
       args = parser.parse_args(argsv)
53
       example(args resource_name, args option_string, args time, args voltage, args sample_
   →rate, args.samples_per_fetch)
56
   def main():
       _main(sys.argv[1:])
58
60
   def test_example():
61
       options = {'simulate': True, 'driver_setup': {'Model': '5164', 'BoardType': 'PXIe', }
62
       example('PXI1Slot2', options, 10, 1.0, 1000.0, 100)
63
   def test_main():
66
       cmd_line = ['--option-string', 'Simulate=1, DriverSetup=Model:5164; BoardType:PXIe',_
   \hookrightarrow
       _main(cmd_line)
68
                                                                                  (continues on next page)
```

```
if __name__ == '__main__':
    main()
```

niscope_fetch_into.py

Listing 3: (niscope_fetch_into.py)

```
#!/usr/bin/python
2
   import argparse
   import niscope
   import numpy
   import pprint
   import sys
   pp = pprint.PrettyPrinter(indent=4, width=80)
10
11
   def example(resource_name, channels, options, length, voltage):
12
       # fetch_into() allows you to preallocate and reuse the destination of the fetched.
13
   →waveforms, which can result in better performance at the expense of the usability of
   \rightarrow fetch().
       channels = [ch.strip() for ch in channels.split(",")]
14
       num_channels = len(channels)
       num records = 5
16
       total_num_wfms = num_channels * num_records
       # preallocate a single array for all samples in all waveforms
18
       # Supported array types are: numpy.float64, numpy.int8, numpy.int16, numpy.int32
19
       # int8, int16, int32 are for fetching unscaled data, which is the fastest way to...
20
   \rightarrow fetch.
       # Gain and Offset are stored in the returned WaveformInfo objects and can be applied.
21
   \rightarrow to the data by the user later.
       wfm = numpy.ndarray(length * total_num_wfms, dtype=numpy.float64)
22
       with niscope Session(resource_name=resource_name, options=options) as session:
23
           session.configure_vertical(range=voltage, coupling=niscope.VerticalCoupling.AC)
24
           session.configure_horizontal_timing(min_sample_rate=50000000, min_num_pts=length,
25
   → ref_position=50.0, num_records=num_records, enforce_realtime=True)
           with session.initiate():
26
                waveforms = session.channels[channels].fetch_into(waveform=wfm, num_
   →records=num_records)
           for i in range(len(waveforms)):
                print(f'Waveform {i} information:')
29
                print(f'{waveforms[i]}\n\n')
                print(f'Samples: {waveforms[i].samples.tolist()}')
31
33
   def _main(argsv):
34
       parser = argparse.ArgumentParser(description='Fetches data directly into au
35
```

(continues on next page)

```
→preallocated numpy array.', formatter_class=argparse.ArgumentDefaultsHelpFormatter)
       parser.add_argument('-n', '--resource-name', default='PXI1Slot2', help='Resource_
    →name of an NI digitizer.')
       parser.add_argument('-c', '--channels', default='0', help='Channel(s) to use')
37
       parser.add_argument('-1', '--length', default=100, type=int, help='Measure record_
38
   →length')
       parser.add_argument('-v', '--voltage', default=1.0, type=float, help='Voltage range_
39
   (V) ')
       parser.add_argument('-op', '--option-string', default='', type=str, help='Option_
40
   →string')
       args = parser.parse_args(argsv)
41
       example(args.resource_name, args.channels, args.option_string, args.length, args.
42
   →voltage)
43
44
   def main():
45
       _main(sys.argv[1:])
47
   def test_example():
49
       options = {'simulate': True, 'driver_setup': {'Model': '5164', 'BoardType': 'PXIe', }
       example('PXI1Slot2', '0, 1', options, 100, 1.0)
51
52
53
   def test_main():
54
       cmd_line = ['--option-string', 'Simulate=1, DriverSetup=Model:5164; BoardType:PXIe',_
55
   \hookrightarrow
       _main(cmd_line)
56
57
58
   if __name__ == '__main__':
       main()
60
```

niscope read.py

Listing 4: (niscope_read.py)

```
#!/usr/bin/python

import argparse
import niscope
import pprint
import sys

pp = pprint.PrettyPrinter(indent=4, width=80)

def example(resource_name, channels, options, length, voltage):
```

(continues on next page)

```
with niscope.Session(resource_name=resource_name, options=options) as session:
12
            session.configure_vertical(range=voltage, coupling=niscope.VerticalCoupling.AC)
13
            session.configure_horizontal_timing(min_sample_rate=50000000, min_num_pts=length,
14
    → ref_position=50.0, num_records=1, enforce_realtime=True)
           waveforms = session.channels[channels].read(num_samples=length)
15
           for i in range(len(waveforms)):
16
                print(f'Waveform {i} information:')
17
               print(str(waveforms[i]) + '\n\n')
18
20
   def _main(argsv):
21
       parser = argparse.ArgumentParser(description='Acquires one record from the given_
22
   → channels.', formatter_class=argparse.ArgumentDefaultsHelpFormatter)
       parser.add_argument('-n', '--resource-name', default='PXI1Slot2', help='Resource_
23
   →name of an NI digitizer.')
       parser.add_argument('-c', '--channels', default='0', help='Channel(s) to use')
24
       parser.add_argument('-l', '--length', default=1000, type=int, help='Measure record_
   →length')
       parser.add_argument('-v', '--voltage', default=1.0, type=float, help='Voltage range_
   (V) ')
       parser.add_argument('-op', '--option-string', default='', type=str, help='Option_
   ⇔string')
       args = parser.parse_args(argsv)
       example(args.resource_name, args.channels, args.option_string, args.length, args.
29
   →voltage)
30
31
   def main():
32
       _main(sys.argv[1:])
33
34
35
   def test_example():
       options = {'simulate': True, 'driver_setup': {'Model': '5164', 'BoardType': 'PXIe', }
37
   ⇔, }
       example('PXI1Slot2', '0', options, 1000, 1.0)
38
40
   def test_main():
       cmd_line = ['--option-string', 'Simulate=1, DriverSetup=Model:5164; BoardType:PXIe', ]
42
   \hookrightarrow
       _main(cmd_line)
43
45
   if __name__ == '__main__':
46
       main()
47
48
```

gRPC Support

Support for using NI-SCOPE over gRPC

SessionInitializationBehavior

class niscope. SessionInitializationBehavior

AUTO

The NI gRPC Device Server will attach to an existing session with the specified name if it exists, otherwise the server will initialize a new session.

Note: When using the Session as a context manager and the context exits, the behavior depends on what happened when the constructor was called. If it resulted in a new session being initialized on the NI gRPC Device Server, then it will automatically close the server session. If it instead attached to an existing session, then it will detach from the server session and leave it open.

INITIALIZE_SERVER_SESSION

Require the NI gRPC Device Server to initialize a new session with the specified name.

Note: When using the Session as a context manager and the context exits, it will automatically close the server session.

ATTACH_TO_SERVER_SESSION

Require the NI gRPC Device Server to attach to an existing session with the specified name.

Note: When using the Session as a context manager and the context exits, it will detach from the server session and leave it open.

GrpcSessionOptions

Collection of options that specifies session behaviors related to gRPC.

Creates and returns an object you can pass to a Session constructor.

Parameters

- grpc_channel (grpc.Channel) Specifies the channel to the NI gRPC Device Server.
- **session_name** (*str*) User-specified name that identifies the driver session on the NI gRPC Device Server.

This is different from the resource name parameter many APIs take as a separate parameter. Specifying a name makes it easy to share sessions across multiple gRPC clients. You can use an empty string if you want to always initialize a new session on the server. To attach to an existing session, you must specify the session name it was initialized with.

• **initialization_behavior** (*niscope.SessionInitializationBehavior*) — Specifies whether it is acceptable to initialize a new session or attach to an existing one, or if only one of the behaviors is desired.

The driver session exists on the NI gRPC Device Server.

4.2 Additional Documentation

Refer to your driver documentation for device-specific information and detailed API documentation.

Refer to the nimi-python Read the Docs project for documentation of versions 1.4.4 of the module or earlier.

CHAPTER

FIVE

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gRPC Features

For driver APIs that support it, passing a GrpcSessionOptions instance as a parameter to Session.__init__() is subject to the NI General Purpose EULA (see NILICENSE).

152 Chapter 5. License

CHAPTER

SIX

INDICES AND TABLES

- genindex
- modindex
- search

PYTHON MODULE INDEX

 $\begin{array}{l} \textbf{n} \\ \textbf{niscope}, 8 \end{array}$

156 Python Module Index

INDEX

A	AREA (niscope.ClearableMeasurement attribute), 130
abort() (in module niscope.Session), 10 absolute_sample_clock_offset (in module niscope.Session), 36 AC (niscope.TriggerCoupling attribute), 137 AC (niscope.VerticalCoupling attribute), 139 AC_ESTIMATE (niscope.ClearableMeasurement attribute), 129	AREA (niscope.ScalarMeasurement attribute), 136 arm_ref_trig_src (in module niscope.Session), 40 ARM_REFERENCE (niscope.WhichTrigger attribute), 140 ARRAY_GAIN (niscope.ArrayMeasurement attribute), 128 ARRAY_INTEGRAL (niscope.ArrayMeasurement attribute), 127 ARRAY_OFFSET (niscope.ArrayMeasurement attribute),
AC_ESTIMATE (niscope.ScalarMeasurement attribute), 136	128 ArrayMeasurement (class in niscope), 127
AC_PLUS_HF_REJECT (niscope.TriggerCoupling attribute), 137 accessory_gain (in module niscope.Session), 102 accessory_offset (in module niscope.Session), 103 acq_arm_source (in module niscope.Session), 38 acquisition_start_time (in module niscope.Session), 37 acquisition_status() (in module niscope.Session), 10 acquisition_type (in module niscope.Session), 37 AcquisitionStatus (class in niscope), 126 AcquisitionType (class in niscope), 127 ADD_CHANNELS (niscope.ArrayMeasurement attribute), 128 add_waveform_processing() (in module niscope)	ATTACH_TO_SERVER_SESSION (niscope.SessionInitializationBehavior attribute), 149 AUTO (niscope.SessionInitializationBehavior attribute), 149 AUTO (niscope.TriggerModifier attribute), 137 AUTO_LEVEL (niscope.TriggerModifier attribute), 137 auto_setup() (in module niscope.Session), 11 AVERAGE_FREQUENCY (niscope.ClearableMeasurement attribute), 129 AVERAGE_FREQUENCY (niscope.ScalarMeasurement attribute), 136 AVERAGE_PERIOD (niscope.ClearableMeasurement attribute), 129 AVERAGE_PERIOD (niscope.ScalarMeasurement attribute), 136
cope.Session), 11 adv_trig_src(in module niscope.Session), 39	В
ADVANCE (niscope.WhichTrigger attribute), 140 advance_trigger_terminal_name (in module niscope.Session), 38 ALL_MEASUREMENTS (niscope.ClearableMeasurement attribute), 129	backlog (in module niscope.Session), 40 BANDPASS (niscope.FilterType attribute), 132 bandpass_filter_enabled (in module niscope.Session), 41
allow_more_records_than_memory (in module nis- cope.Session), 39 AMPLITUDE (niscope.ClearableMeasurement attribute), 129	BANDSTOP (niscope.FilterType attribute), 132 BASETOP (niscope.PercentageMethod attribute), 133 BESSEL_FILTER (niscope.ArrayMeasurement attribute), 128
AMPLITUDE (niscope.ScalarMeasurement attribute), 135 ANALOG_DETECTION_CIRCUIT (niscope.RefTriggerDetectorLocation attribute), 134 ANY_FIELD (niscope.VideoTriggerEvent attribute), 140	binary_sample_width (in module niscope.Session), 41 BLACKMAN (niscope.FIRFilterWindow attribute), 131 BLACKMAN_WINDOW (niscope.ArrayMeasurement attribute), 128 BUTTERWORTH_FILTER (niscope.ArrayMeasurement at-
ANY_LINE (niscope. VideoTriggerEvent attribute), 140	tribute), 128

C	data_transfer_preferred_packet_size (in module
cable_sense_mode (in module niscope.Session), 42	niscope.Session), 46
cable_sense_signal_enable (in module nis-	DC (niscope.TriggerCoupling attribute), 137
cope.Session), 43	DC (niscope.VerticalCoupling attribute), 139
cable_sense_voltage (in module niscope.Session), 43	DC_ESTIMATE (niscope.ClearableMeasurement at-
CableSenseMode (class in niscope), 128	tribute), 129
<pre>channel_count (in module niscope.Session), 44</pre>	DC_ESTIMATE (niscope.ScalarMeasurement attribute),
channel_enabled (in module niscope.Session), 44	136
channel_terminal_configuration (in module nis-	DDC (niscope.AcquisitionType attribute), 127
cope.Session), 45	DDC_OUTPUT (niscope.RefTriggerDetectorLocation
channels (niscope.Session.niscope.Session attribute),	attribute), 134
126	DERIVATIVE (niscope.ArrayMeasurement attribute), 127
CHEBYSHEV_FILTER (niscope.ArrayMeasurement at-	device_temperature (in module niscope.Session), 46
tribute), 128	DIFFERENTIAL (niscope.TerminalConfiguration at-
<pre>clear_waveform_measurement_stats() (in module</pre>	tribute), 136
niscope.Session), 12	DIGITAL (niscope.TriggerType attribute), 138 disable() (in module niscope.Session), 21
clear_waveform_processing() (in module nis-	DISABLED (niscope.CableSenseMode attribute), 128
cope.Session), 13	DIVIDE_CHANNELS (niscope.ArrayMeasurement at-
ClearableMeasurement (class in niscope), 129	tribute), 128
close() (in module niscope.Session), 13	DriverError, 141
commit() (in module niscope.Session), 13	DriverNotInstalledError, 142
COMPLETE (niscope.AcquisitionStatus attribute), 126	DriverTooNewError, 142
configure_chan_characteristics() (in module nis-	DriverTooOldError, 142
cope.Session), 13	DriverWarning, 142
<pre>configure_equalization_filter_coefficients()</pre>	DUTY_CYCLE_NEG (niscope.ClearableMeasurement at-
configure_horizontal_timing() (in module nis-	tribute), 130
cope.Session), 14	DUTY_CYCLE_NEG (niscope.ScalarMeasurement at-
configure_trigger_digital() (in module nis-	tribute), 135
cope.Session), 15	DUTY_CYCLE_POS (niscope.ClearableMeasurement at-
configure_trigger_edge() (in module nis-	tribute), 130
cope.Session), 16	${\tt DUTY_CYCLE_POS} (niscope. Scalar Measurement at-$
configure_trigger_hysteresis() (in module nis-	tribute), 135
cope.Session), 17	Е
<pre>configure_trigger_immediate() (in module nis-</pre>	E
cope.Session), 18	EDGE (niscope.TriggerType attribute), 137
<pre>configure_trigger_software() (in module nis-</pre>	EIGHT_TAP_HANNING (nis-
cope.Session), 18	$cope. Flex FIR Antialias Filter Type \qquad attribute),$
<pre>configure_trigger_video() (in module nis-</pre>	132
cope.Session), 19	EITHER (niscope.GlitchPolarity attribute), 133
<pre>configure_trigger_window() (in module nis-</pre>	EITHER (niscope.RuntPolarity attribute), 134
cope.Session), 20	EITHER (niscope. WidthPolarity attribute), 141
<pre>configure_vertical() (in module niscope.Session),</pre>	enable_dc_restore (in module niscope.Session), 48
21	enable_time_interleaved_sampling (in module nis-
CYCLE_AREA (niscope.ClearableMeasurement attribute),	cope.Session), 48
130	enabled_channels (in module niscope.Session), 47
CYCLE_AREA (niscope.ScalarMeasurement attribute), 136	end_of_acquisition_event_output_terminal (in
D	module niscope. Session), 49
	<pre>end_of_acquisition_event_terminal_name (in</pre>
data_transfer_block_size (in module nis-	end_of_record_event_output_terminal (in module
cope.Session), 45	niscope.Session), 50
data_transfer_maximum_bandwidth (in module nis-	end_of_record_event_terminal_name (in module
cope.Session), 46	niscope.Session), 50

end_of_record_to_advance_trigger_holdoff (in module niscope.Session), 51 ENTERING (niscope.TriggerWindowMode attribute), 138 ENTERING_OR_LEAVING (niscope.TriggerWindowMode attribute), 138	FilterType (class in niscope), 132 FIRFilterWindow (class in niscope), 131 FLAT_TOP (niscope.FIRFilterWindow attribute), 131 FLAT_TOP_WINDOW (niscope.ArrayMeasurement attribute), 127
equalization_filter_enabled (in module nis-	flex_fir_antialias_filter_type (in module nis-
<pre>cope.Session), 51 equalization_num_coefficients (in module nis- cope.Session), 52</pre>	cope.Session), 54 FlexFIRAntialiasFilterType (class in niscope), 132 FLEXRES (niscope.AcquisitionType attribute), 127
Error, 141 EXACT_NUM_AVERAGES (niscope.RISMethod attribute), 133	FOURTYEIGHT_TAP_HANNING (nis- cope.FlexFIRAntialiasFilterType attribute), 132
<pre>export_attribute_configuration_buffer() (in</pre>	FOURTYEIGHT_TAP_STANDARD (nis- cope.FlexFIRAntialiasFilterType attribute), 132
<pre>ule niscope.Session), 22 exported_advance_trigger_output_terminal (in</pre>	<pre>fpga_bitfile_path (in module niscope.Session), 54 FREQUENCY (niscope.ClearableMeasurement attribute), 129</pre>
<pre>module niscope.Session), 52 exported_ref_trigger_output_terminal (in mod-</pre>	FREQUENCY (niscope.ScalarMeasurement attribute), 135
<pre>ule niscope.Session), 53 exported_start_trigger_output_terminal (in</pre>	G
module niscope.Session), 53	<pre>get_channel_names() (in module niscope.Session), 28 get_equalization_filter_coefficients() (in</pre>
FALL_SLEW_RATE (niscope.ClearableMeasurement at-	<pre>module niscope.Session), 29 get_ext_cal_last_date_and_time() (in module nis-</pre>
tribute), 129 FALL_SLEW_RATE (niscope.ScalarMeasurement attribute), 136	<pre>cope.Session), 29 get_ext_cal_last_temp() (in module nis- cope.Session), 29</pre>
FALL_TIME (niscope.ClearableMeasurement attribute), 129	<pre>get_self_cal_last_date_and_time() (in module</pre>
FALL_TIME (niscope.ScalarMeasurement attribute), 135 fetch() (in module niscope.Session), 22	<pre>get_self_cal_last_temp() (in module nis- cope.Session), 30</pre>
fetch_array_measurement() (in module nis- cope.Session), 24	GLITCH (niscope.TriggerType attribute), 138 glitch_condition (in module niscope.Session), 55
<pre>fetch_into() (in module niscope.Session), 25 fetch_measurement_stats() (in module nis-</pre>	glitch_polarity (in module niscope.Session), 55 glitch_width (in module niscope.Session), 55 GlitchCondition (class in niscope), 132
FetchRelativeTo (class in niscope), 131 FFT_AMP_SPECTRUM_DB (niscope.ArrayMeasurement attribute), 128 FFT_AMP_SPECTRUM_VOLTS_RMS (nis-	GlitchPolarity (class in niscope), 133 GND (niscope. VerticalCoupling attribute), 139 GREATER (niscope. GlitchCondition attribute), 132 GrpcSessionOptions (class in niscope), 149
cope.ArrayMeasurement attribute), 127 FFT_AMPLITUDE (niscope.ClearableMeasurement	Н
attribute), 129 FFT_AMPLITUDE (niscope.ScalarMeasurement attribute), 136	HAMMING (niscope.FIRFilterWindow attribute), 131 HAMMING_WINDOW (niscope.ArrayMeasurement attribute), 128
FFT_FREQUENCY (niscope.ClearableMeasurement attribute), 129	HANNING (niscope.FIRFilterWindow attribute), 131 HANNING_WINDOW (niscope.ArrayMeasurement at-
FFT_FREQUENCY (niscope.ScalarMeasurement attribute), 136	tribute), 127 HF_REJECT (niscope.TriggerCoupling attribute), 137
FFT_PHASE_SPECTRUM (niscope.ArrayMeasurement attribute), 127	high_pass_filter_frequency (in module nis- cope.Session), 56
FIELD1 (niscope.VideoTriggerEvent attribute), 140 FIELD2 (niscope.VideoTriggerEvent attribute), 140	HIGH_REF_VOLTS (niscope.ClearableMeasurement attribute), 130

HIGH_REF_VOLTS (niscope.ScalarMeasurement attribute), 136	LIMITED_BIN_WIDTH (niscope.RISMethod attribute), 134
HIGHPASS (niscope.FilterType attribute), 132	LINE_NUMBER (niscope. VideoTriggerEvent attribute), 140
horz_enforce_realtime (in module niscope.Session),	lock() (in module niscope.Session), 31
56	<pre>logical_name (in module niscope.Session), 64</pre>
horz_min_num_pts (in module niscope.Session), 57	LOW_REF_VOLTS (niscope.ClearableMeasurement
horz_num_records (in module niscope.Session), 57	attribute), 130
horz_record_length (in module niscope.Session), 58	LOW_REF_VOLTS (niscope.ScalarMeasurement attribute),
horz_record_ref_position (in module nis-	136
cope.Session), 58	LOWHIGH (niscope.PercentageMethod attribute), 133
horz_sample_rate (in module niscope.Session), 59	LOWPASS (niscope.FilterType attribute), 132
horz_time_per_record (in module niscope.Session),	N.4
59	M
HYSTERESIS (niscope.TriggerType attribute), 137	M_PAL (niscope.VideoSignalFormat attribute), 139
ı	master_enable (in module niscope.Session), 64
I	<pre>max_input_frequency (in module niscope.Session), 65</pre>
IMMEDIATE (niscope.TriggerType attribute), 138	<pre>max_real_time_sampling_rate (in module nis-</pre>
<pre>import_attribute_configuration_buffer() (in</pre>	cope.Session), 65
module niscope.Session), 30	<pre>max_ris_rate (in module niscope.Session), 66</pre>
<pre>import_attribute_configuration_file() (in mod-</pre>	meas_array_gain (in module niscope.Session), 66
ule niscope.Session), 31	meas_array_offset (in module niscope.Session), 67
IN_PROGRESS (niscope.AcquisitionStatus attribute), 126	meas_chan_high_ref_level (in module nis-
INCOMPLETE (niscope.RISMethod attribute), 133	cope.Session), 67
INITIALIZE_SERVER_SESSION (nis-	meas_chan_low_ref_level (in module nis-
cope.SessionInitializationBehavior attribute), 149	cope.Session), 68
	meas_chan_mid_ref_level (in module nis-
initiate() (in module niscope. Session), 31	<pre>cope.Session), 69 meas_filter_center_freq (in module nis-</pre>
<pre>input_clock_source (in module niscope.Session), 59 input_impedance (in module niscope.Session), 60</pre>	meas_filter_center_freq (in module nis- cope.Session), 69
instrument_firmware_revision (in module nis-	meas_filter_cutoff_freq (in module nis-
cope.Session), 61	cope.Session), 70
instrument_manufacturer (in module nis-	meas_filter_order (in module niscope.Session), 71
cope.Session), 61	meas_filter_ripple (in module niscope.Session), 71
instrument_model (in module niscope.Session), 62	meas_filter_taps (in module niscope.Session), 72
instruments (niscope.Session.niscope.Session at-	meas_filter_transient_waveform_percent (in
tribute), 126	module niscope.Session), 72
INTEGRAL (niscope.ClearableMeasurement attribute),	<pre>meas_filter_type (in module niscope.Session), 73</pre>
130	<pre>meas_filter_width (in module niscope.Session), 74</pre>
INTEGRAL (niscope.ScalarMeasurement attribute), 136	meas_fir_filter_window (in module nis-
<pre>interleaving_offset_correction_enabled (in</pre>	cope.Session), 74
module niscope.Session), 62	<pre>meas_high_ref (in module niscope.Session), 75</pre>
InvalidRepeatedCapabilityError, 142	meas_hysteresis_percent (in module nis-
INVERSE (niscope.ArrayMeasurement attribute), 127	cope.Session), 75
<pre>io_resource_descriptor (in module nis- cope.Session), 63</pre>	meas_interpolation_sampling_factor (in module niscope.Session), 76
is_probe_comp_on (in module niscope.Session), 63	<pre>meas_last_acq_histogram_size (in module nis- cope.Session), 76</pre>
L	meas_low_ref (in module niscope.Session), 77
LAST_ACQ_HISTOGRAM (niscope.ArrayMeasurement at-	<pre>meas_mid_ref (in module niscope.Session), 77</pre>
tribute), 127	meas_other_channel (in module niscope.Session), 78
LEAVING (niscope.TriggerWindowMode attribute), 138	meas_percentage_method (in module nis-
LESS (niscope.GlitchCondition attribute), 132	cope.Session), 78
LF_REJECT (niscope.TriggerCoupling attribute), 137	<pre>meas_polynomial_interpolation_order (in module</pre>

<pre>meas_ref_level_units (in module niscope.Session), 80</pre>	NO_TRIGGER_MOD (niscope.TriggerModifier attribute), 137
meas_time_histogram_high_time (in module nis-	NONE (niscope.FIRFilterWindow attribute), 131
cope.Session), 80	NONE (niscope.RuntTimeCondition attribute), 135
meas_time_histogram_high_volts (in module nis-	NORMAL (niscope.AcquisitionType attribute), 127
cope.Session), 81	NOW (niscope.FetchRelativeTo attribute), 131
meas_time_histogram_low_time (in module nis-	NTSC (niscope. Video Signal Format attribute), 139
cope.Session), 82	NISC (niscope. videosignaii ormai aurionie), 13)
*	0
meas_time_histogram_low_volts (in module nis-	
cope.Session), 82	ON_DEMAND (niscope.CableSenseMode attribute), 128
meas_time_histogram_size (in module nis-	onboard_memory_size (in module niscope.Session), 86
cope.Session), 83	Option (class in niscope), 133
meas_voltage_histogram_high_volts (in module	output_clock_source (in module niscope.Session), 86
niscope.Session), 83	OUTSIDE (niscope.RuntTimeCondition attribute), 135
<pre>meas_voltage_histogram_low_volts(in module nis-</pre>	OUTSIDE (niscope.WidthCondition attribute), 141
cope.Session), 84	OVERSHOOT (niscope.ClearableMeasurement attribute),
meas_voltage_histogram_size (in module nis-	129
cope.Session), 85	OVERSHOOT (niscope.ScalarMeasurement attribute), 136
MID_REF_VOLTS (niscope.ClearableMeasurement	_
attribute), 130	P
MID_REF_VOLTS (niscope.ScalarMeasurement attribute),	PAL (niscope.VideoSignalFormat attribute), 139
136	PERCENTAGE (niscope.RefLevelUnits attribute), 134
MIN_NUM_AVERAGES (niscope.RISMethod attribute), 133	PercentageMethod (class in niscope), 133
min_sample_rate (in module niscope.Session), 85	PERIOD (niscope. Clearable Measurement attribute), 129
MINMAX (niscope.PercentageMethod attribute), 133	PERIOD (niscope.ScalarMeasurement attribute), 135
module	PHASE_DELAY (niscope.ClearableMeasurement at-
niscope, 8	tribute), 130
MULTI_ACQ_AVERAGE (niscope.ArrayMeasurement	PHASE_DELAY (niscope.ScalarMeasurement attribute),
attribute), 128	136
MULTI_ACQ_AVERAGE (niscope.ClearableMeasurement	
attribute), 129	pll_lock_status (in module niscope.Session), 87
MULTI_ACQ_TIME_HISTOGRAM (nis-	points_done (in module niscope.Session), 87
cope.ArrayMeasurement attribute), 127	poll_interval (in module niscope.Session), 88 POLYNOMIAL_INTERPOLATION (nis-
MULTI_ACQ_TIME_HISTOGRAM (nis-	· ·
cope.ClearableMeasurement attribute), 129	cope.ArrayMeasurement attribute), 127
MULTI_ACQ_VOLTAGE_HISTOGRAM (nis-	POSITIVE (niscope. GlitchPolarity attribute), 133
cope.ArrayMeasurement attribute), 127	POSITIVE (niscope.RuntPolarity attribute), 134
MULTI_ACQ_VOLTAGE_HISTOGRAM (nis-	POSITIVE (niscope.TriggerSlope attribute), 137
cope.ClearableMeasurement attribute), 129	rositive (mscope. viaeot otarny anrionte), 139
MULTIPLY_CHANNELS (niscope.ArrayMeasurement	POSITIVE (niscope. WidthPolarity attribute), 141
attribute), 127	PRESHOOT (niscope.ClearableMeasurement attribute),
annome), 127	
	129
N	129 PRESHOOT (niscope.ScalarMeasurement attribute), 136
N	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131
NEGATIVE (niscope.GlitchPolarity attribute), 133	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32 probe_compensation_signal_stop() (in module niscope.Session)
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139 NEGATIVE (niscope.WidthPolarity attribute), 141	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139 NEGATIVE (niscope.WidthPolarity attribute), 141 niscope	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32 probe_compensation_signal_stop() (in module niscope.Session), 32
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139 NEGATIVE (niscope.WidthPolarity attribute), 141 niscope module, 8	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32 probe_compensation_signal_stop() (in module niscope.Session), 32 R
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139 NEGATIVE (niscope.WidthPolarity attribute), 141 niscope module, 8 NO_MEASUREMENT (niscope.ArrayMeasurement at-	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32 probe_compensation_signal_stop() (in module niscope.Session), 32 R read() (in module niscope.Session), 32
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139 NEGATIVE (niscope.WidthPolarity attribute), 141 niscope module, 8 NO_MEASUREMENT (niscope.ArrayMeasurement attribute), 127	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32 probe_compensation_signal_stop() (in module niscope.Session), 32 R read() (in module niscope.Session), 32 READ_POINTER (niscope.FetchRelativeTo attribute), 131
NEGATIVE (niscope.GlitchPolarity attribute), 133 NEGATIVE (niscope.RuntPolarity attribute), 134 NEGATIVE (niscope.TriggerSlope attribute), 137 NEGATIVE (niscope.VideoPolarity attribute), 139 NEGATIVE (niscope.WidthPolarity attribute), 141 niscope module, 8 NO_MEASUREMENT (niscope.ArrayMeasurement at-	PRESHOOT (niscope.ScalarMeasurement attribute), 136 PRETRIGGER (niscope.FetchRelativeTo attribute), 131 probe_attenuation (in module niscope.Session), 88 probe_compensation_signal_start() (in module niscope.Session), 32 probe_compensation_signal_stop() (in module niscope.Session), 32 R read() (in module niscope.Session), 32

${\tt ready_for_advance_event_terminal_name}\ (in\ mod-$	S
ule niscope.Session), 89	<pre>samp_clk_timebase_div (in module niscope.Session).</pre>
<pre>ready_for_ref_event_output_terminal (in module</pre>	100
niscope.Session), 90	<pre>samp_clk_timebase_rate (in module nis-</pre>
ready_for_ref_event_terminal_name (in module	cope.Session), 101
niscope.Session), 90	<pre>samp_clk_timebase_src (in module niscope.Session),</pre>
ready_for_start_event_output_terminal(in mod-	101
ule niscope.Session), 91	<pre>sample_clock_timebase_multiplier (in module nis-</pre>
ready_for_start_event_terminal_name (in module	cope.Session), 100
niscope.Session), 91	sample_mode (in module niscope.Session), 100
record_arm_source (in module niscope.Session), 92	ScalarMeasurement (class in niscope), 135
records_done (in module niscope.Session), 92	SECAM (niscope.VideoSignalFormat attribute), 139
ref_clk_rate (in module niscope.Session), 92	<pre>self_cal() (in module niscope.Session), 34</pre>
ref_trig_tdc_enable (in module niscope.Session), 94	SELF_CALIBRATE_ALL_CHANNELS (niscope.Option at-
ref_trigger_detector_location (in module nis-	tribute), 133
cope.Session), 93	<pre>self_test() (in module niscope.Session), 35</pre>
ref_trigger_minimum_quiet_time (in module nis-	SelfTestError, 142
cope.Session), 93	<pre>send_software_trigger_edge() (in module nis-</pre>
ref_trigger_terminal_name (in module nis-	cope.Session), 35
cope.Session), 94	serial_number (in module niscope.Session), 102
REFERENCE (niscope. Which Trigger attribute), 140	Session (class in niscope), 8
RefLevelUnits (class in niscope), 134	SessionInitializationBehavior (class in niscope),
RefTriggerDetectorLocation (class in niscope), 134	149
reset() (in module niscope.Session), 34 reset_device() (in module niscope.Session), 34	simulate (in module niscope. Session), 104
reset_with_defaults() (in module niscope.Session), 54	SINGLE_ENDED (niscope.TerminalConfiguration at-
34	tribute), 136
resolution (in module niscope.Session), 95	SIXTEEN_TAP_HANNING (nis-
RESTORE_EXTERNAL_CALIBRATION (niscope.Option at-	cope.FlexFIRAntialiasFilterType attribute),
tribute), 133	132
ris_in_auto_setup_enable (in module nis-	SLOPE_EITHER (niscope.TriggerSlope attribute), 137
cope.Session), 95	SOFTWARE (niscope.TriggerType attribute), 138
ris_method (in module niscope.Session), 96	specific_driver_description (in module nis-
ris_num_averages (in module niscope.Session), 96	cope.Session), 104 specific_driver_revision (in module nis-
RISE_SLEW_RATE (niscope.ClearableMeasurement at-	specific_driver_revision (in module nis- cope.Session), 105
tribute), 129	specific_driver_vendor (in module nis-
RISE_SLEW_RATE (niscope.ScalarMeasurement at-	cope.Session), 105
tribute), 136	START (niscope.FetchRelativeTo attribute), 131
RISE_TIME (niscope.ClearableMeasurement attribute),	START (niscope.WhichTrigger attribute), 140
129	start_to_ref_trigger_holdoff (in module nis-
RISE_TIME (niscope.ScalarMeasurement attribute), 135	cope.Session), 105
RISMethod (class in niscope), 133	start_trigger_terminal_name (in module nis-
RpcError, 142	cope.Session), 106
RUNT (niscope.TriggerType attribute), 138	STATUS_UNKNOWN (niscope.AcquisitionStatus attribute),
<pre>runt_high_threshold (in module niscope.Session), 97</pre>	126
runt_low_threshold (in module niscope.Session), 97	SUBTRACT_CHANNELS (niscope.ArrayMeasurement
runt_polarity (in module niscope.Session), 98	attribute), 128
runt_time_condition (in module niscope.Session), 98	supported_instrument_models (in module nis-
runt_time_high_limit (in module niscope.Session),	cope.Session), 106
99	_
runt_time_low_limit (in module niscope.Session), 99	Т
RuntPolarity (class in niscope), 134	tclk (in module niscope.Session), 119
RuntTimeCondition (class in niscope), 135	TerminalConfiguration (class in niscope), 136

TIME_DELAY (niscope.ClearableMeasurement attribute),	TV (niscope.TriggerType attribute), 138
130	tv_trigger_event (in module niscope.Session), 114
TIME_DELAY (niscope.ScalarMeasurement attribute), 136	tv_trigger_line_number (in module nis-
TIME_HISTOGRAM_HITS (nis-	cope.Session), 114
cope.ClearableMeasurement attribute), 131	<pre>tv_trigger_polarity (in module niscope.Session),</pre>
TIME_HISTOGRAM_MAX (niscope.ClearableMeasurement	115
attribute), 130	tv_trigger_signal_format (in module nis-
TIME_HISTOGRAM_MEAN (nis-	cope.Session), 115
cope.ClearableMeasurement attribute), 130	
TIME_HISTOGRAM_MEAN_PLUS_2_STDEV (nis-	U
cope.ClearableMeasurement attribute), 131	UNBALANCED_DIFFERENTIAL (nis-
TIME_HISTOGRAM_MEAN_PLUS_3_STDEV (nis-	cope.TerminalConfiguration attribute), 136
cope.ClearableMeasurement attribute), 131	unlock() (in module niscope.Session), 36
TIME_HISTOGRAM_MEAN_PLUS_STDEV (nis-	
cope.ClearableMeasurement attribute), 131	UnsupportedConfigurationError, 141
TIME_HISTOGRAM_MEDIAN (nis-	use_spec_initial_x (in module niscope.Session), 115
cope.ClearableMeasurement attribute), 130	V
•	•
TIME_HISTOGRAM_MIN (niscope.ClearableMeasurement	vertical_coupling (in module niscope.Session), 116
attribute), 131	vertical_offset (in module niscope.Session), 116
TIME_HISTOGRAM_MODE (nis-	vertical_range (in module niscope.Session), 117
cope.ClearableMeasurement attribute), 130	VerticalCoupling (class in niscope), 139
TIME_HISTOGRAM_NEW_HITS (nis-	VIDEO_1080I_50_FIELDS_PER_SECOND (nis-
cope.ClearableMeasurement attribute), 131	cope.VideoSignalFormat attribute), 140
TIME_HISTOGRAM_PEAK_TO_PEAK (nis-	VIDEO_1080I_59_94_FIELDS_PER_SECOND (nis-
cope.ClearableMeasurement attribute), 131	cope.VideoSignalFormat attribute), 140
TIME_HISTOGRAM_STDEV (nis-	VIDEO_1080I_60_FIELDS_PER_SECOND (nis-
cope.ClearableMeasurement attribute), 130	cope.VideoSignalFormat attribute), 140
TRIANGLE (niscope.FIRFilterWindow attribute), 131	VIDEO_1080P_24_FRAMES_PER_SECOND (nis-
TRIANGLE_WINDOW (niscope.ArrayMeasurement at-	cope.VideoSignalFormat attribute), 140
tribute), 128	VIDEO_480I_59_94_FIELDS_PER_SECOND (nis-
TRIGGER (niscope.FetchRelativeTo attribute), 132	cope.VideoSignalFormat attribute), 139
trigger_auto_triggered (in module nis-	VIDEO_480I_60_FIELDS_PER_SECOND (nis-
cope.Session), 107	cope.VideoSignalFormat attribute), 139
<pre>trigger_coupling (in module niscope.Session), 107</pre>	VIDEO_480P_59_94_FRAMES_PER_SECOND (nis-
<pre>trigger_delay_time (in module niscope.Session), 108</pre>	cope.VideoSignalFormat attribute), 139
trigger_holdoff (in module niscope.Session), 108	VIDEO_480P_60_FRAMES_PER_SECOND (nis-
trigger_hysteresis (in module niscope.Session), 109	· ·
trigger_impedance (in module niscope.Session), 109	cope.VideoSignalFormat attribute), 139 VIDEO_576I_50_FIELDS_PER_SECOND (nis-
trigger_level (in module niscope.Session), 110	
trigger_modifier (in module niscope.Session), 110	cope.VideoSignalFormat attribute), 139
trigger_slope (in module niscope.Session), 111	VIDEO_576P_50_FRAMES_PER_SECOND (nis-
trigger_source (in module niscope.Session), 111	cope.VideoSignalFormat attribute), 139
trigger_type (in module niscope.Session), 111	VIDEO_720P_50_FRAMES_PER_SECOND (nis-
trigger_window_high_level (in module nis-	cope.VideoSignalFormat attribute), 140
cope.Session), 112	VIDEO_720P_59_94_FRAMES_PER_SECOND (nis-
	cope.VideoSignalFormat attribute), 140
	VIDEO_720P_60_FRAMES_PER_SECOND (nis-
cope.Session), 113	cope.VideoSignalFormat attribute), 140
trigger_window_mode (in module niscope.Session),	VideoPolarity (class in niscope), 139
113	VideoSignalFormat (class in niscope), 139
TriggerCoupling (class in niscope), 137	VideoTriggerEvent (class in niscope), 140
TriggerModifier (class in niscope), 137	VOLTAGE_AVERAGE (niscope.ClearableMeasurement at-
TriggerSlope (class in niscope), 137	tribute), 129
TriggerType (class in niscope), 137	VOLTAGE_AVERAGE (niscope.ScalarMeasurement at-
TriggerWindowMode (class in niscope), 138	tribute), 135

VOLTAGE_BASE (niscope.ClearableMeasurement at-	VOLTAGE_MIN (niscope.ScalarMeasurement attribute) 135
tribute), 130 VOLTAGE_BASE (niscope.ScalarMeasurement attribute),	VOLTAGE_PEAK_TO_PEAK (nis-
136	cope.ClearableMeasurement attribute), 129
VOLTAGE_BASE_TO_TOP (nis-	VOLTAGE_PEAK_TO_PEAK (niscope.ScalarMeasuremen
cope.ClearableMeasurement attribute), 130	attribute), 135
VOLTAGE_BASE_TO_TOP (niscope.ScalarMeasurement	VOLTAGE_RMS (niscope.ClearableMeasurement at
attribute), 136	tribute), 129
VOLTAGE_CYCLE_AVERAGE (nis-	VOLTAGE_RMS (niscope.ScalarMeasurement attribute)
cope.ClearableMeasurement attribute), 129	135
VOLTAGE_CYCLE_AVERAGE (niscope.ScalarMeasurement	VOLTAGE_TOP (niscope.ClearableMeasurement at
attribute), 135	tribute), 129
VOLTAGE_CYCLE_RMS (niscope.ClearableMeasurement	VOLTAGE_TOP (niscope.ScalarMeasurement attribute)
attribute), 129	136
VOLTAGE_CYCLE_RMS (niscope.ScalarMeasurement attribute), 135	VOLTS (niscope.RefLevelUnits attribute), 134
VOLTAGE_HIGH (niscope.ClearableMeasurement at-	W
tribute), 129	
VOLTAGE_HIGH (niscope.ScalarMeasurement attribute),	WhichTrigger (class in niscope), 140 WIDTH (niscope.TriggerType attribute), 138
135	width_condition (in module niscope.Session), 118
VOLTAGE_HISTOGRAM_HITS (nis-	width_high_threshold (in module niscope.Session), 118
cope.ClearableMeasurement attribute), 130	118
VOLTAGE_HISTOGRAM_MAX (nis-	width_low_threshold (in module niscope.Session)
cope.ClearableMeasurement attribute), 130	119
VOLTAGE_HISTOGRAM_MEAN (nis-	WIDTH_NEG (niscope.ClearableMeasurement attribute)
cope.ClearableMeasurement attribute), 130	130
VOLTAGE_HISTOGRAM_MEAN_PLUS_2_STDEV (nis-	WIDTH_NEG (niscope.ScalarMeasurement attribute), 135
cope.ClearableMeasurement attribute), 130	width_polarity (in module niscope.Session), 119
VOLTAGE_HISTOGRAM_MEAN_PLUS_3_STDEV (nis-	WIDTH_POS (niscope.ClearableMeasurement attribute)
cope.ClearableMeasurement attribute), 130	130
VOLTAGE_HISTOGRAM_MEAN_PLUS_STDEV (nis-	WIDTH_POS (niscope.ScalarMeasurement attribute), 135
cope.ClearableMeasurement attribute), 130	WidthCondition (class in niscope), 141
VOLTAGE_HISTOGRAM_MEDIAN (nis-	WidthPolarity (class in niscope), 141
cope.ClearableMeasurement attribute), 130 VOLTAGE_HISTOGRAM_MIN (nis-	WINDOW (niscope.TriggerType attribute), 138
cope.ClearableMeasurement attribute), 130	WINDOWED_FIR_FILTER (niscope.ArrayMeasurement at
VOLTAGE_HISTOGRAM_MODE (nis-	tribute), 128
cope.ClearableMeasurement attribute), 130	WITHIN (niscope.RuntTimeCondition attribute), 135 WITHIN (niscope.WidthCondition attribute), 141
VOLTAGE_HISTOGRAM_NEW_HITS (nis-	willin (mscope. widin Condition dirionie), 141
cope.ClearableMeasurement attribute), 130	
VOLTAGE_HISTOGRAM_PEAK_TO_PEAK (nis-	
cope.ClearableMeasurement attribute), 130	
VOLTAGE_HISTOGRAM_STDEV (nis-	
cope.ClearableMeasurement attribute), 130	
VOLTAGE_LOW (niscope.ClearableMeasurement at-	
tribute), 129	
VOLTAGE_LOW (niscope.ScalarMeasurement attribute),	
135	
VOLTAGE_MAX (niscope.ClearableMeasurement at-	
tribute), 129 VOLTAGE_MAX (niscope.ScalarMeasurement attribute),	
135 (niscope.Scalarmeasurement attribute),	
VOLTAGE_MIN (niscope.ClearableMeasurement at-	
tribute), 129	